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## **Module-3**

### **Lecture-15**

**Static Stability and Control - Elevator Control  
power, Elevator Angle to trim and Estimation of  
Stick Fixed Neutral Point**

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# Longitudinal Control

Control of the pitch attitude of the airplane can be achieved by deflecting the elevator.

## Elevator Effectiveness

When the elevator is deflected, it changes the lift and the pitching moment of the airplane.

Change in lift for the airplane,  $\Delta C_L$ ;

$$\Delta C_L = C_{L_{\delta e}} \delta e$$

where,

$$C_{L_{\delta e}} = \frac{\partial C_L}{\partial \delta e}$$
$$(C_L)_{a/c} = C_{L_\alpha} \alpha + C_{L_{\delta e}} \delta e$$

Similarly change in the pitching moment,  $\Delta C_m$

$$\Delta C_m = C_{m_{\delta e}} \delta e$$

where,

$$C_{m_{\delta e}} = \frac{\partial C_m}{\partial \delta e}$$

$C_{m_{\delta e}}$ : Elevator Control Power

$$(C_m)_{a/c} = C_{m_o} + C_{m_\alpha} \alpha + C_{m_{\delta e}} \delta e$$

The variation of  $C_m$  with  $\delta e$  is presented in Figure 1. Kindly note that Slope  $\partial C_m / \partial \alpha$  remains same when elevator is deflected.

**Expression for  $C_{L_{\delta e}}$  and  $C_{m_{\delta e}}$**  The change in lift of the airplane due to deflecting the elevator is equal to the change in lift force acting on the tail

$$\Delta L = \Delta L_t = \Delta C_{L_t} q_t S_t$$

Let,

$q_t$  - dynamic pressure at tail

$$\Delta C_L = \frac{\Delta L_t}{\frac{1}{2} \rho V^2 S_w} = \frac{S_t}{S_w} \eta \frac{\partial C_{L_t}}{\partial \delta e} \delta e$$

$\frac{\partial C_{L_t}}{\partial \delta e}$ : Elevator Effectiveness

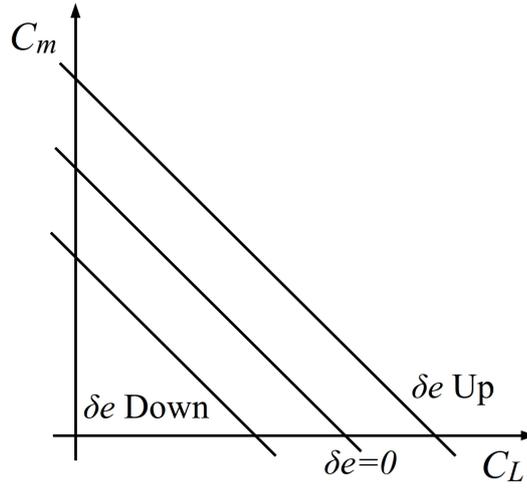


Figure 1: Graph showing relation between  $C_m$  and  $C_L$  or  $\alpha$

The elevator effectiveness is proportional to the size of the flap being used.

$$\frac{\partial C_{L_t}}{\partial \delta e} = \frac{\partial C_{L_t}}{\partial \alpha, t} \cdot \frac{\partial \alpha, t}{\partial \delta e} = C_{L_{\alpha, t}} \tau$$

Typical value of  $\tau$  lies between 0.2 to 0.6.

$$\begin{aligned} \Delta C_L &= \frac{S_t}{S_w} \eta \frac{\partial C_{L_t}}{\partial \delta e} \delta e = \frac{S_t}{S_w} \eta C_{L_{\alpha, t}} \tau \delta e \\ \Rightarrow C_{L_{\delta e}} &= \frac{S_t}{S_w} \eta C_{L_{\alpha, t}} \tau \end{aligned} \quad (1)$$

The increment in pitching moment,  $\Delta C_m$

$$\begin{aligned} \Delta C_m &= -\Delta C_L \frac{l_t}{\bar{c}} = -\frac{S_t}{S_w} \eta C_{L_{\alpha, t}} \tau \left( \frac{l_t}{\bar{c}} \right) \delta e \\ \Delta C_m &= -\left( \frac{S_t l_t}{S_w \bar{c}} \right) \eta C_{L_{\alpha, t}} \tau \delta e \\ \Rightarrow C_{m_{\delta e}} &= -V_H \eta C_{L_{\alpha, t}} \tau \end{aligned} \quad (2)$$

This is known as elevator control power.

## Elevator angle to trim

An aircraft is said to be trimmed if the net forces and moments acting on the airplane are zero.

$$C_m = C_{m_o} + C_{m_\alpha} \alpha + C_{m_{\delta e}} \delta e$$

At trim,  $C_m = 0$

$$0 = C_{m_o} + C_{m_\alpha} \alpha_{trim} + C_{m_{\delta e}} \delta e_{trim}$$

The lift coefficient at trim is  $C_{L_{trim}}$

$$\begin{aligned} C_{L_{trim}} &= C_{L_\alpha} \alpha_{trim} + C_{L_{\delta e}} (\delta e)_{trim} \\ \alpha_{trim} &= \frac{[C_{L_{trim}} - C_{L_{\delta e}} (\delta e)_{trim}]}{C_{L_\alpha}} \end{aligned} \quad (3)$$

Combining  $\alpha_{trim}$  and  $C_{L_{trim}}$  equations,

We have

$$\delta e_{trim} = \left[ \frac{C_{m_o} C_{L_\alpha} + C_{m_\alpha} C_{L_{trim}}}{C_{m_{\delta e}} C_{L_\alpha} - C_{m_\alpha} C_{L_{\delta e}}} \right]$$

or

$$\delta e_{trim} = -\frac{C_{m_o}}{C_{m_{\delta e}} - \frac{C_{m_\alpha}}{C_{L_\alpha}} C_{L_{\delta e}}} - \frac{\frac{C_{m_\alpha}}{C_{L_\alpha}} C_{L_{trim}}}{C_{m_{\delta e}} - \frac{C_{m_\alpha}}{C_{L_\alpha}} C_{L_{\delta e}}}$$

Assuming,

$$\frac{C_{m_\alpha}}{C_{L_\alpha}} C_{L_{\delta e}} \ll C_{m_{\delta e}}$$

We have,

$$\begin{aligned} \delta e_{trim} &= -\frac{C_{m_o}}{C_{m_{\delta e}}} - \frac{\frac{C_{m_\alpha}}{C_{L_\alpha}} C_{L_{trim}}}{C_{m_{\delta e}}} \\ \frac{C_{m_\alpha}}{C_{L_\alpha}} &= \frac{\partial C_m}{\partial C_L} \end{aligned}$$

so

$$\begin{aligned} \delta e_{trim} &= -\frac{C_{m_o}}{C_{m_{\delta e}}} - \left( \frac{\frac{\partial C_m}{\partial C_L}}{C_{m_{\delta e}}} \right) C_{L_{trim}} \\ (\delta e)_{trim} &= \delta e_o + \left( \frac{\partial \delta e}{\partial C_L} \right)_{trim} C_{L_{trim}} \end{aligned} \quad (4)$$

where

$$\begin{aligned} \delta e_o &= -\frac{C_{m_o}}{C_{m_{\delta e}}} \\ \frac{\partial \delta e}{\partial C_{L_{trim}}} &= -\frac{\frac{\partial C_m}{\partial C_L}}{C_{m_{\delta e}}} \end{aligned}$$

$$\delta e_{trim} = \delta e_o + \left( \frac{\partial \delta e}{\partial C_{L_{trim}}} \right) C_{L_{trim}} \quad (5)$$

This equation can be used to estimate the value of elevator deflection required to trim a given aircraft at a particular  $C_{L_{trim}}$

### Estimation of Neutral Point (Stick Fixed)

$$\delta e_{trim} = \delta e_o + \left( \frac{\partial \delta e}{\partial C_{L_{trim}}} \right) C_{L_{trim}}$$

$$\frac{\partial \delta e_{trim}}{\partial C_{L_{trim}}} = - \frac{\frac{\partial C_m}{\partial C_L}}{C_{m_{\delta e}}}$$

Neutral point is the *c.g.* location at which  $\partial C_m / \partial C_L = 0$

Therefore, at neutral point,

$$\frac{\partial \delta e_{trim}}{\partial C_{L_{trim}}} = 0$$

### Flight test to estimate Stick Fixed Neutral Point

Above equation can be used to estimate stick fixed neutral point.

- Fly at different center of gravity configuration and execute cruise
- Estimate corresponding

$$C_{L_{trim}} = \frac{2W/S}{\frac{1}{2}\rho V^2}$$

and record  $\delta e$

- Plot  $\delta e_{trim}$  v/s  $C_{L_{trim}}$
- Cross plot  $[\partial \delta e / \partial C_L]_{trim}$  v/s  $\bar{x}_{cg}$  to get neutral point.

