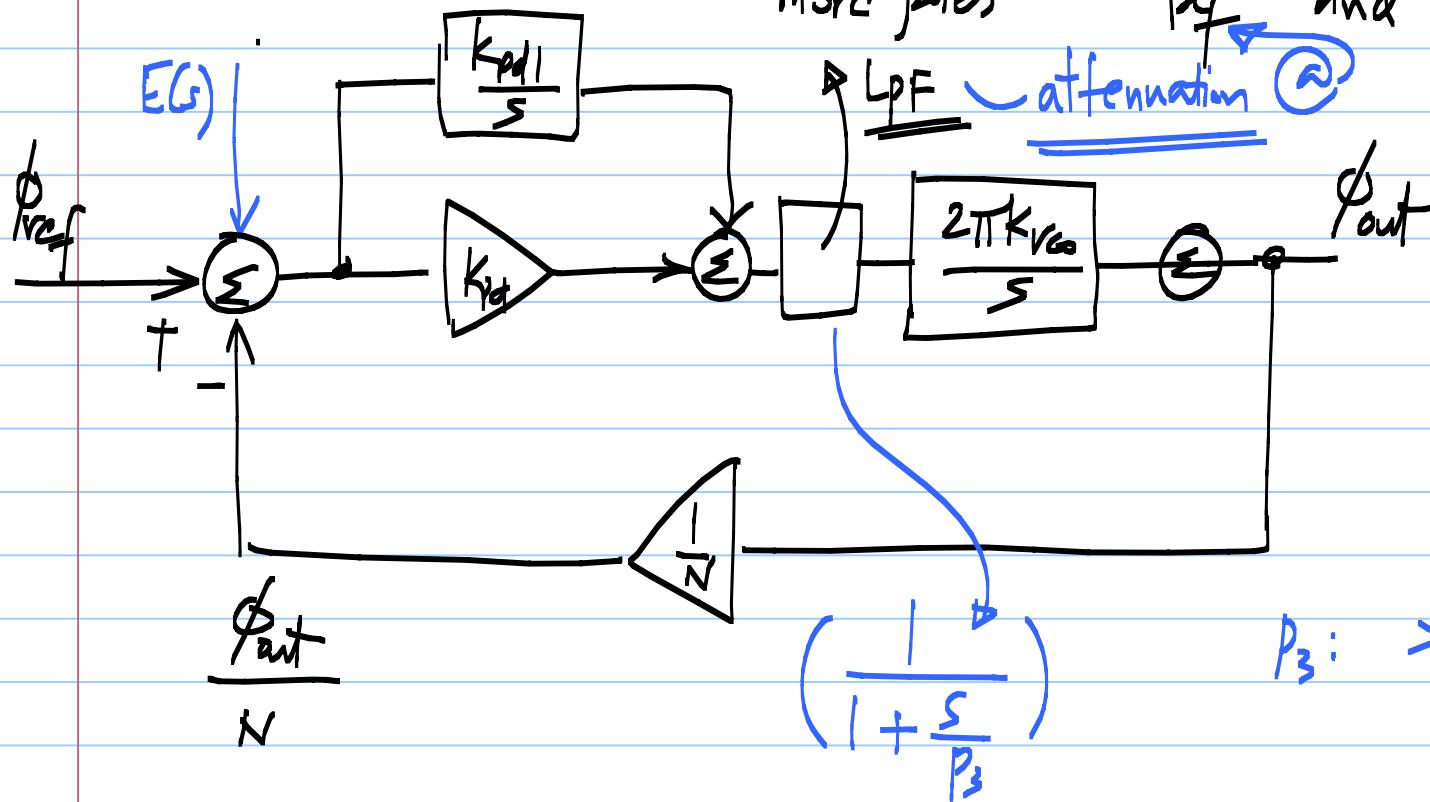


Lecture 5D :



$\epsilon(t)$: Contains components at
 more poles f_{cf} and its harmonics
 well beyond
 the unity
 loop gain
 frequency

$$P_3 : \gg \omega_{vco}, \omega_{loop}$$

Phase :

$\phi_{ref}(t)$: continuous-time

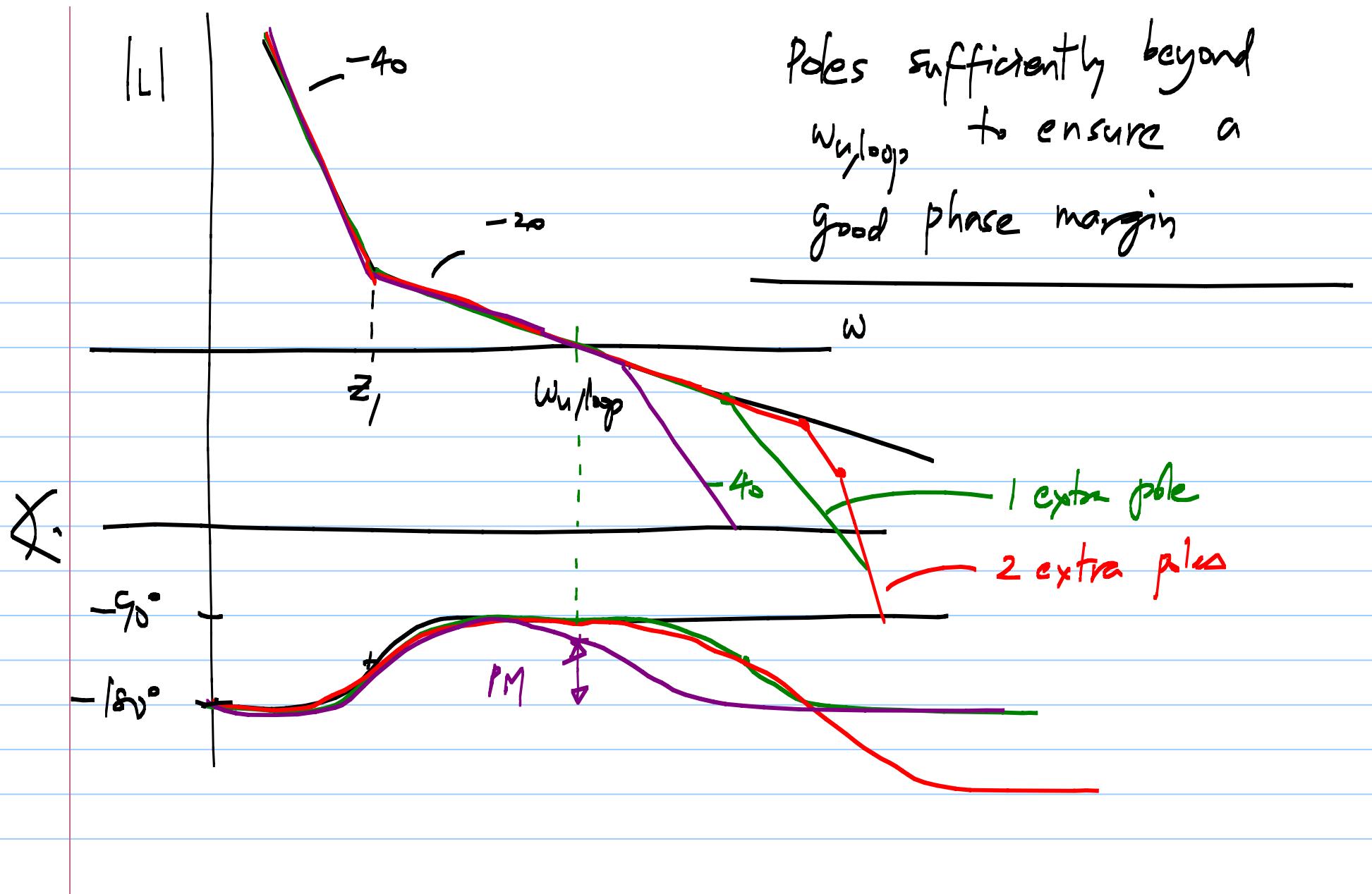
r_{ref}

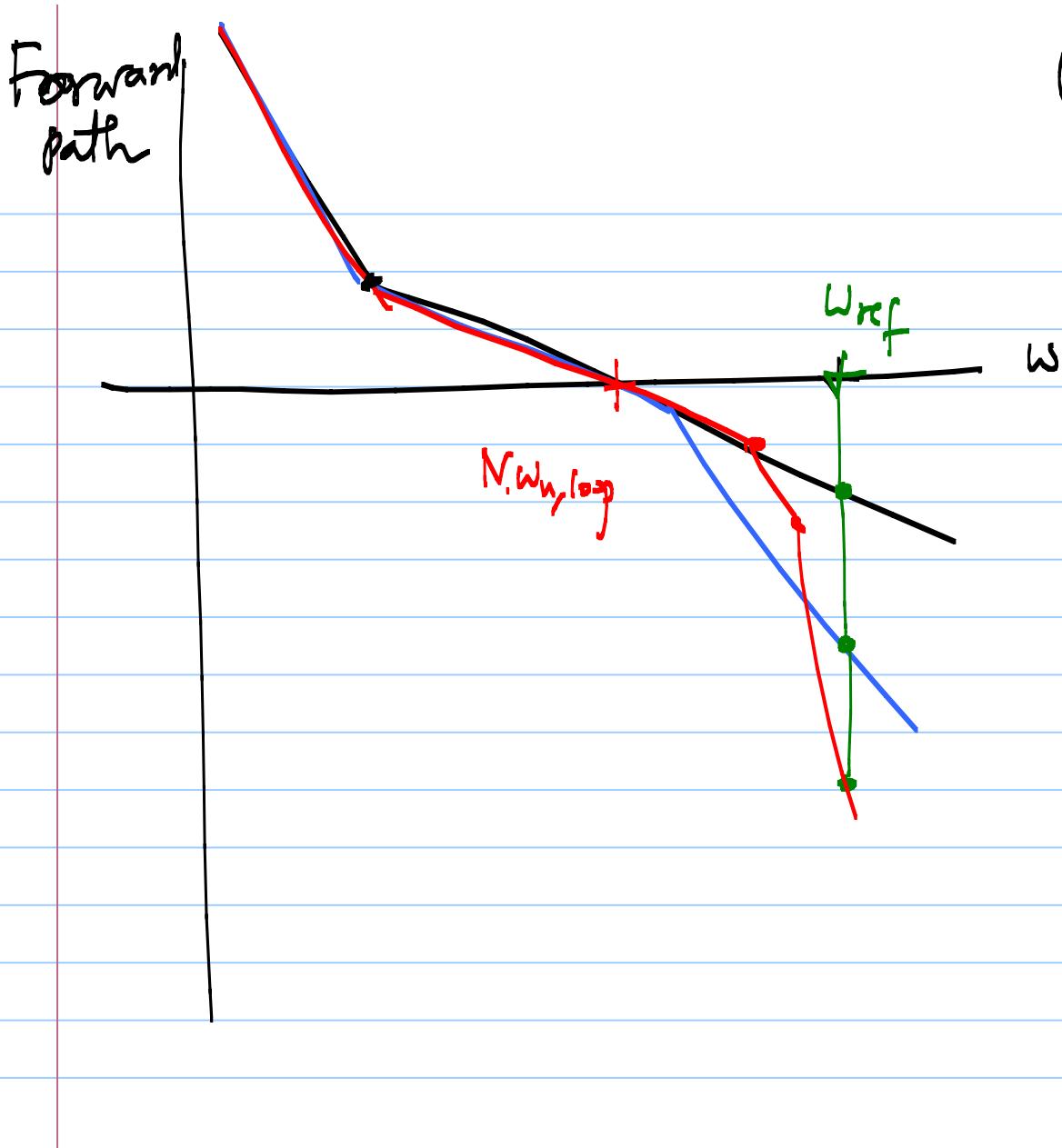
Sampled data signal - sampled at f_{ref}

Can only measure the phase
at the zero crossings

Continuous-time approximation valid if

$$f_{ref} \gg \frac{w_{loop}}{2\pi}$$

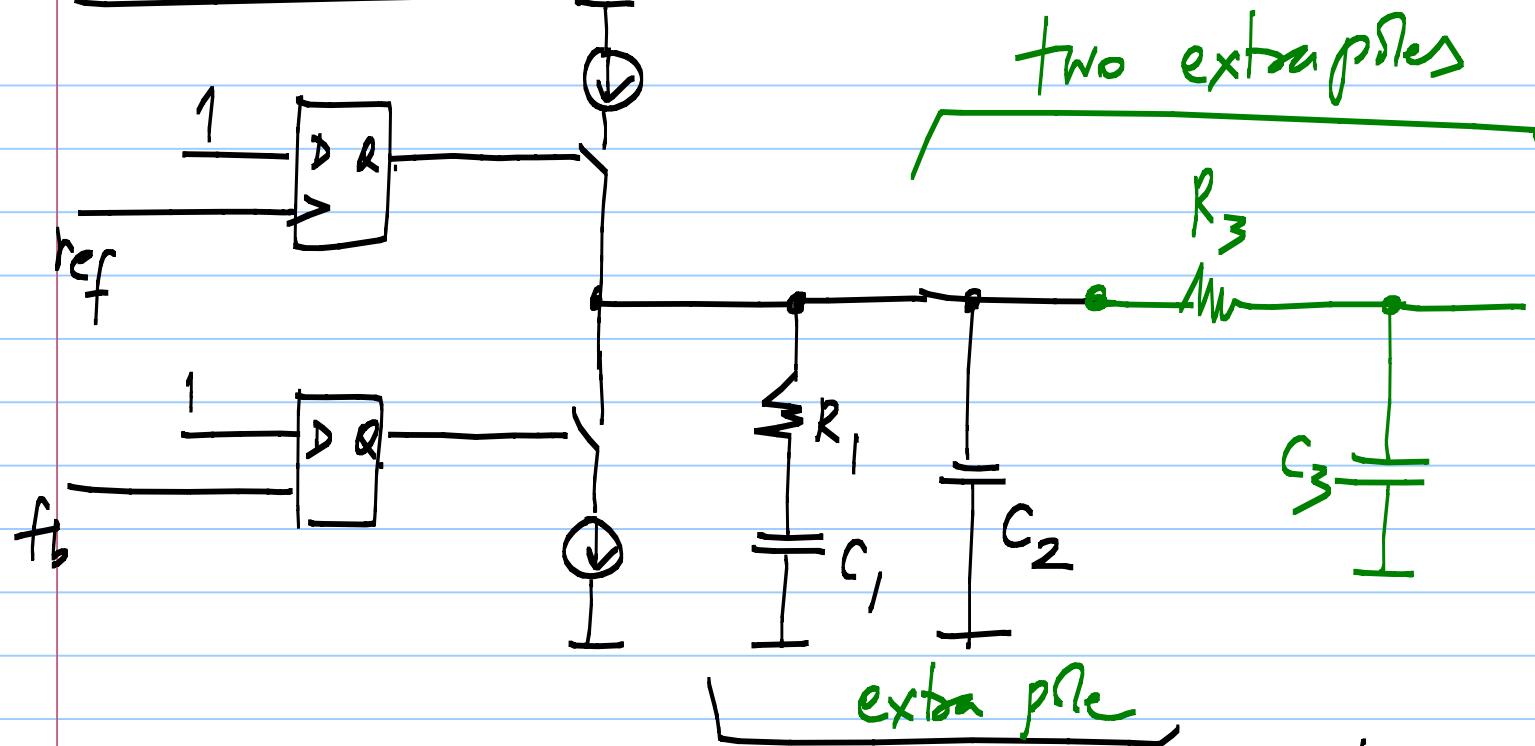




$$\left(k_{p1} + \frac{k_{p1,1}}{s} \right) \cdot \frac{2\pi K_{vco}}{s} \left(\frac{1}{1 + \sum P_3} \right)$$

Poles have to be
below the reference
frequency in order
to attenuate
feedthrough components.

Type II PLL w/ charge pump:

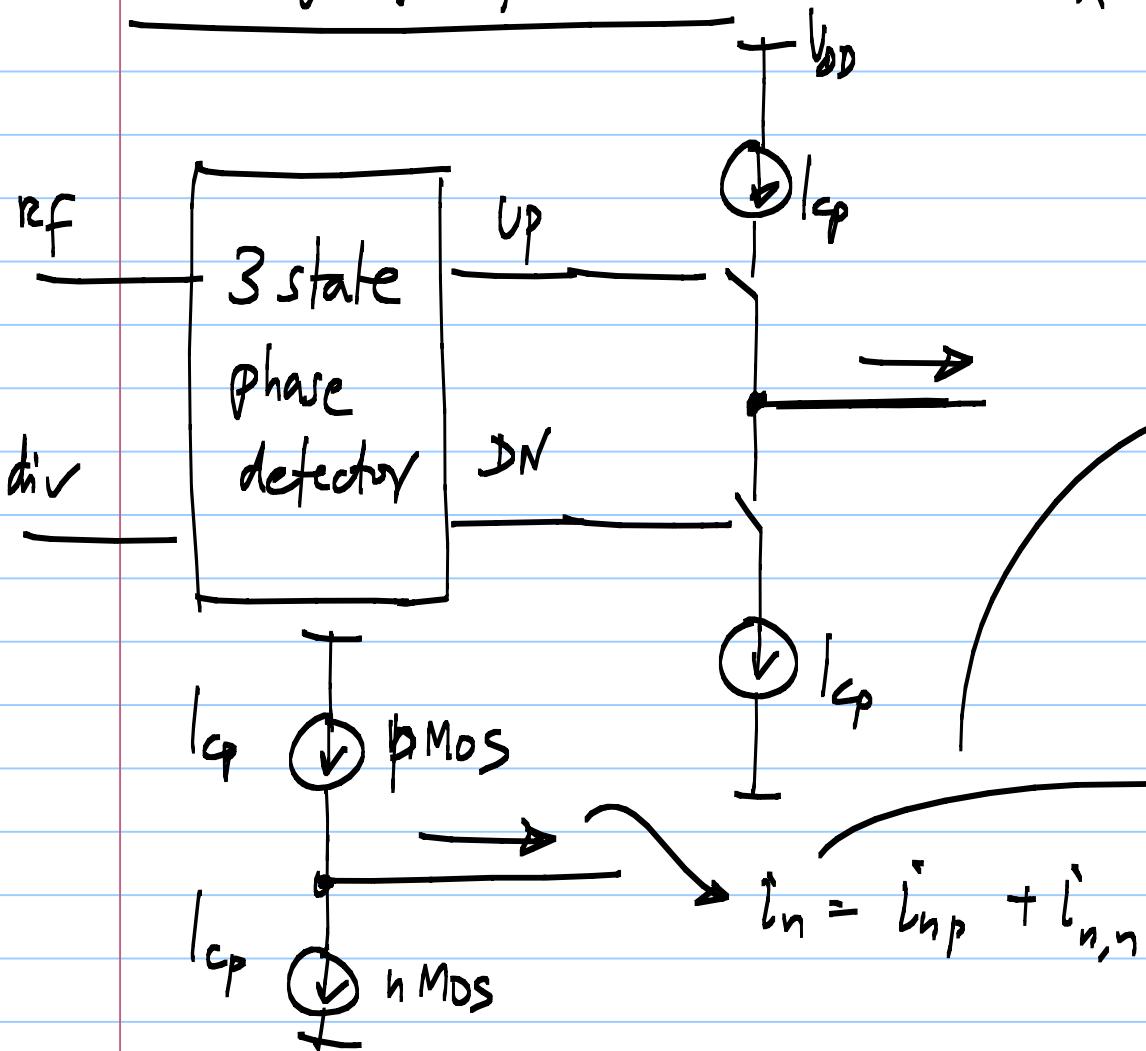


1 extra pole : add $C_2 \cdot$ pole @ $\frac{1}{R_1 \frac{(g \cdot C_2)}{C_1 + C_2}}$ rad/s

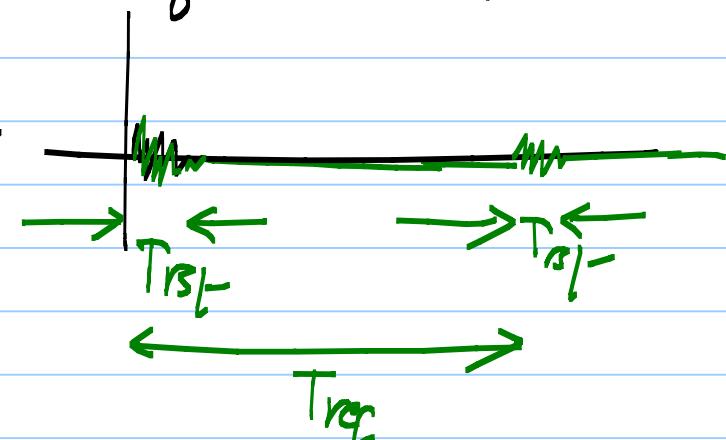
Random noise in a PLL:

- * Reference oscillator: phase noise (ϕ_{ref})
- * VCO : phase noise (ϕ_{vco})
- * Charge pump noise (current source noise)
- * Loop filter noise (e.g. resistor)

Charge pump noise:



* UP, DN: on for a duration of T_{rst} (reset time of the PD)



$$f_n = \left(S_{inp} + S_{inn} \right) \cdot \frac{T_{rst}}{T_{rf}}$$

$$\frac{\phi_{\text{out}}}{\phi_{\text{ref}}} = N \cdot \frac{1 + \frac{s}{z_1}}{1 + \frac{s}{z_1} + \frac{s^2}{\omega_{\text{loop}} z_1}} = \frac{\phi_{\text{out}}}{\phi_{n, cp}}$$

input ref.
noise

of the charge
pump

$$S_{\phi_{n, cp}} = \frac{s_{i_n}}{\left(\frac{1}{c_p/2\pi}\right)^2} = \left(\frac{2\pi}{I_{cp}}\right)^2 \left[s_{i_{\text{mp}}} + s_{i_{\text{nn}}} \right] \left(\frac{T_{\text{rst}}}{T_{\text{ref}}} \right)$$

$$S_{\text{out}, cp} = \left(\frac{2\pi}{I_{cp}}\right)^2 \left[s_{i_{\text{mp}}} + s_{i_{\text{nn}}} \right] \left(\frac{T_{\text{rst}}}{T_{\text{ref}}} \right) \cdot \left| \frac{\phi_{\text{out}}}{\phi_{n, cp}} \right|^2$$

$$S_{out,CP} = \left(\frac{2\pi}{I_C} \right)^2 \left[S_{mp} + S_{nn} \right] \cdot \left(\frac{T_{ref}}{T_{ref}} \right) \cdot \left| \frac{\phi_{out}}{\phi_{in,CP}} \right|^2$$

* Reduce T_{ref}/T_{ref}

$$\frac{4\pi^2}{I_C^2} \frac{8}{3} kT (g_{mp} + g_{nn}) \left(\frac{T_{ref}}{T_{ref}} \right) \left| \frac{\phi_{out}}{\phi_{in,CP}} \right|^2$$

* Increase I_C

– reduce R $k_m = \frac{I_C}{2\pi}$

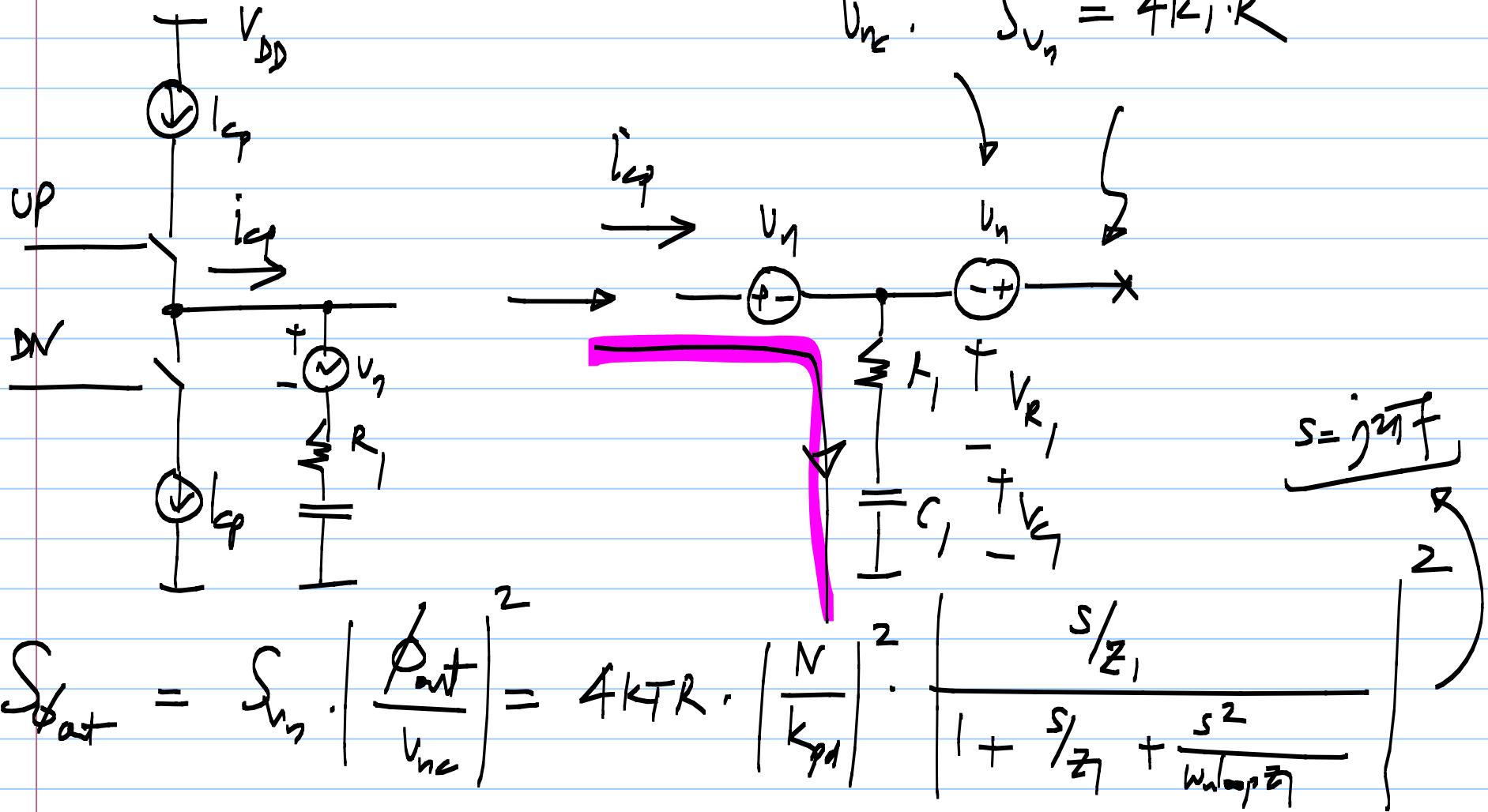
– increase C $k_{pd,1} = \frac{I_C}{2\pi C}$

$$= \frac{4\pi^2}{I_C} \frac{8}{3} kT \left[\frac{g_{mp}}{I_C} + \frac{g_{nn}}{I_C} \right] \left(\frac{T_{ref}}{T_{ref}} \right) \left| \frac{\phi_{out}}{\phi_{in,CP}} \right|^2$$

* Increase $\left\{ \frac{V_{asp} - V_{Tp}}{2}, \frac{V_{asn} - V_{Tn}}{2} \right\}$

$$\left[\frac{V_{asp} - V_{Tp}}{2} + \frac{V_{asn} - V_{Tn}}{2} \right]$$

Contribution of the loop filter:



$$S_{\phi_{out}} = 4kT R \cdot \left| \frac{N}{k_p} \right|^2 \cdot \left| \frac{s/z_1}{1 + \frac{s}{z_1} + \frac{s^2}{w_{loop} \cdot z_1}} \right|^2$$

$s = j2\pi f$

* Reduce R

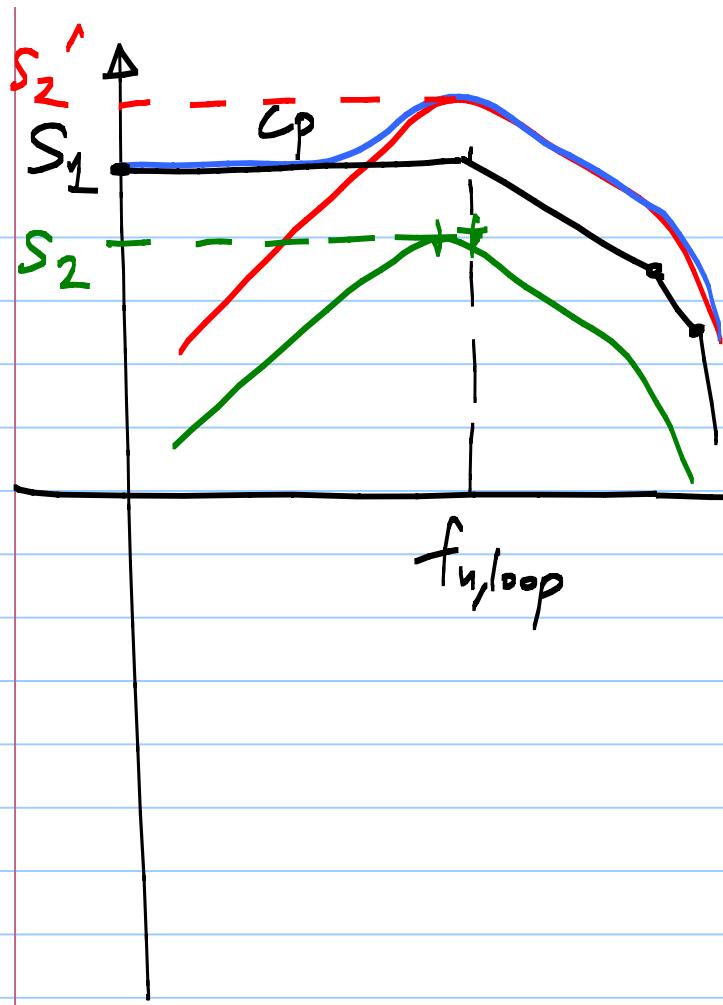
└ Increase I_{op} $k_{pd} = I_{op} \cdot R / 2\pi$

└ Increase C $k_{pd,1} = I_{op} / 2\pi C$

Impedance scaling

* Increase k_{pd}

└ Reduce k_{rc}



Noise in ϕ_{out} due
to charge pump:

$$\frac{4\pi^2}{L_{Cp}^2} \cdot \frac{8}{3} kT (g_{mp} + g_{mn}) \left(\frac{T_{rst}}{T_{ref}} \right) \left| \frac{\phi_{out}}{\phi_{incp}} \right|^2$$

$$S_1 = \frac{4\pi^2}{L_{Cp}^2} \cdot \frac{8}{3} kT (g_{mp} + g_{mn}) \left(\frac{T_{rst}}{T_{ref}} \right) \cdot N^2 \text{ rad}^2 / \text{Hz}$$

$$S_2 = 4kTR \left| \frac{N}{K_{p1}} \right|^2$$

