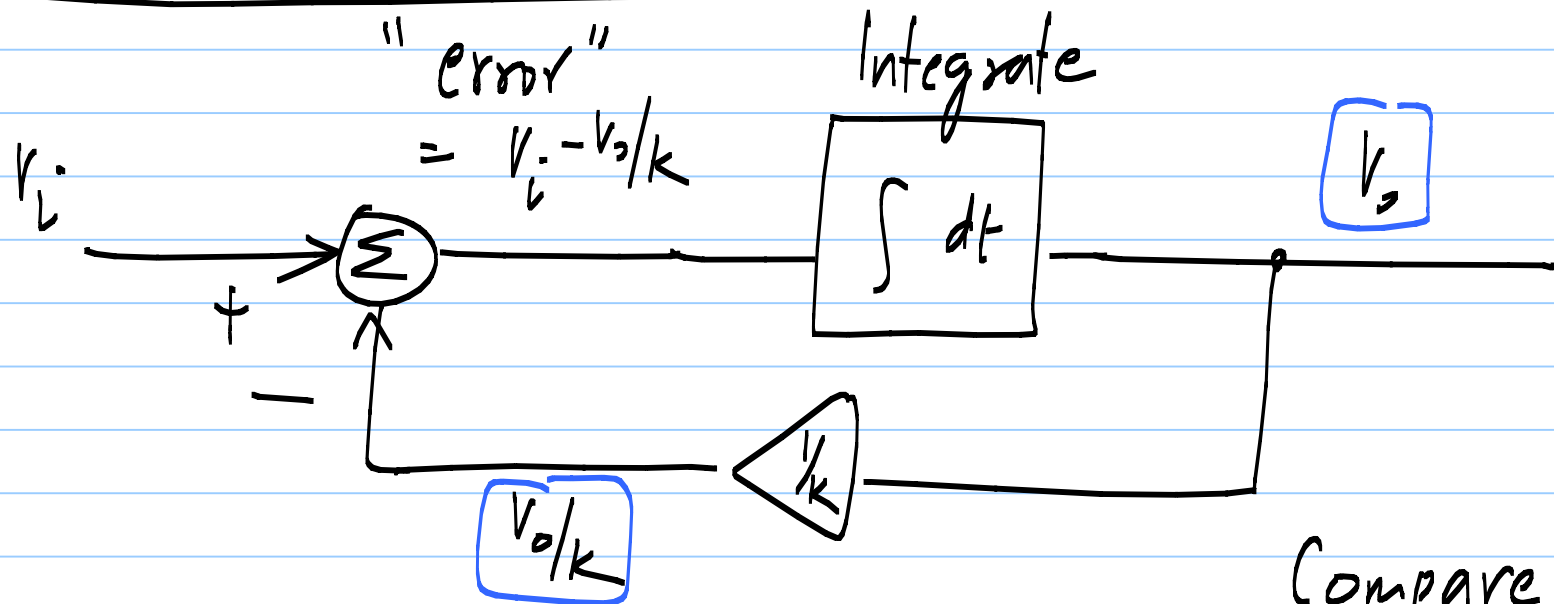


error = 0 \Rightarrow integrator
o/p = constant

Amplifier using negative feedback

Note Title

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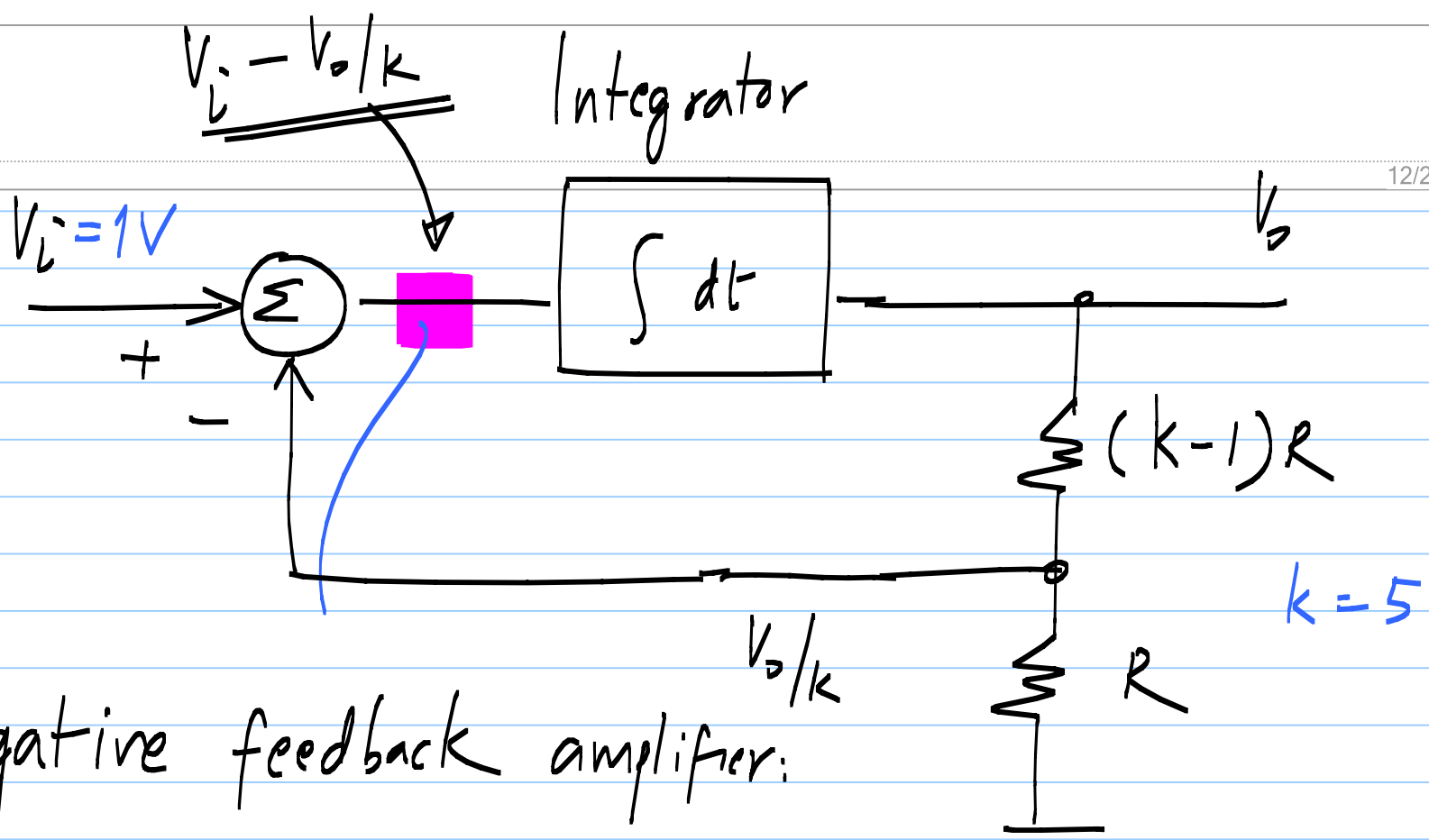


I'd like to make $v_o = k v_i$

Compare actual o/p to the desired o/p.

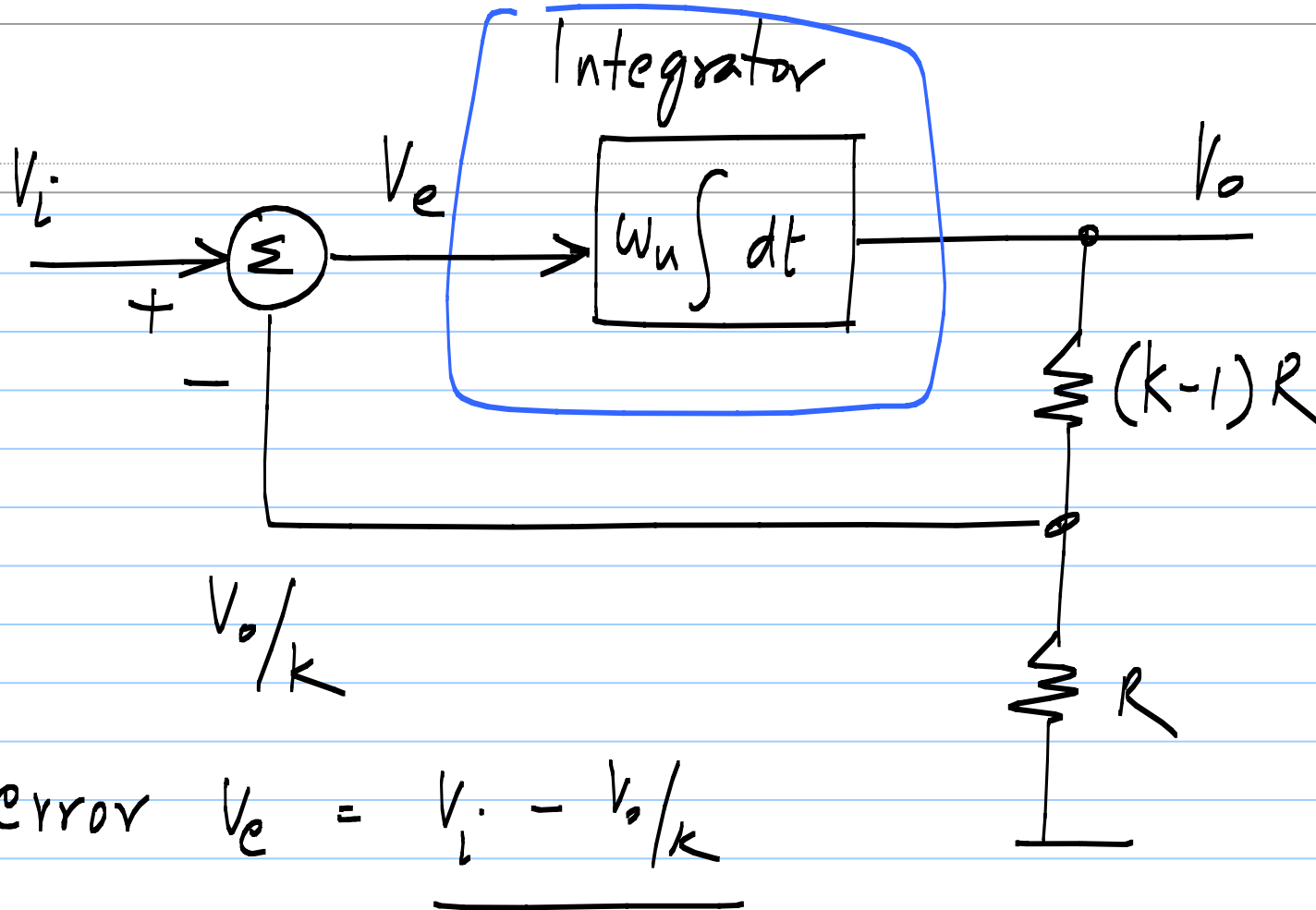
≡ I'd like to make $\frac{v_o}{k} = v_i$

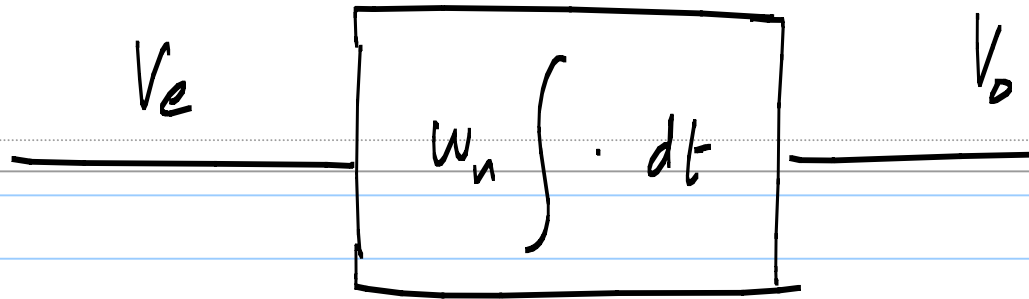
error: $\left(\frac{v_o}{k} - v_i \right)$



Negative feedback amplifier:

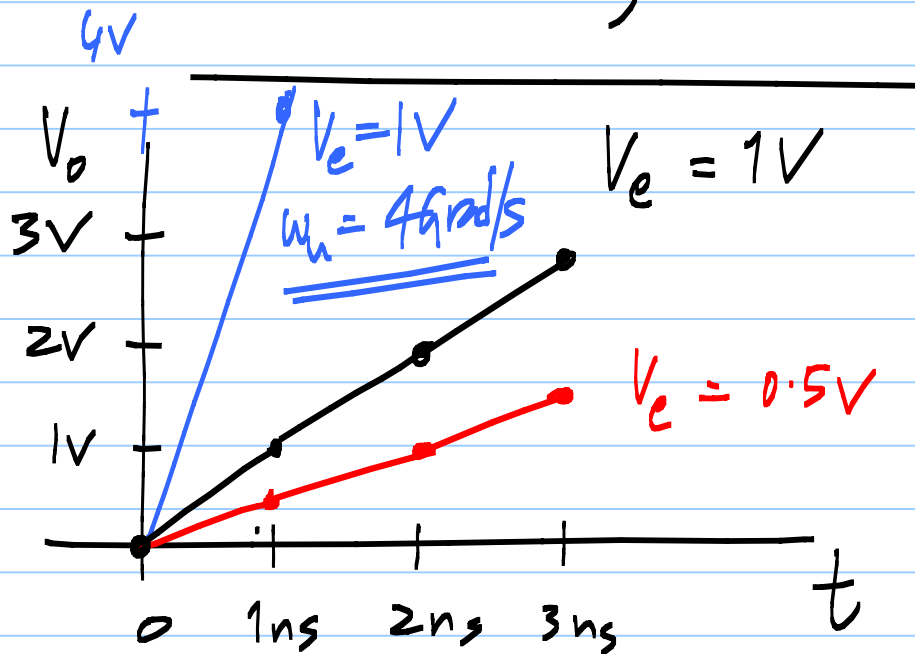
- Integrate the error to drive the output





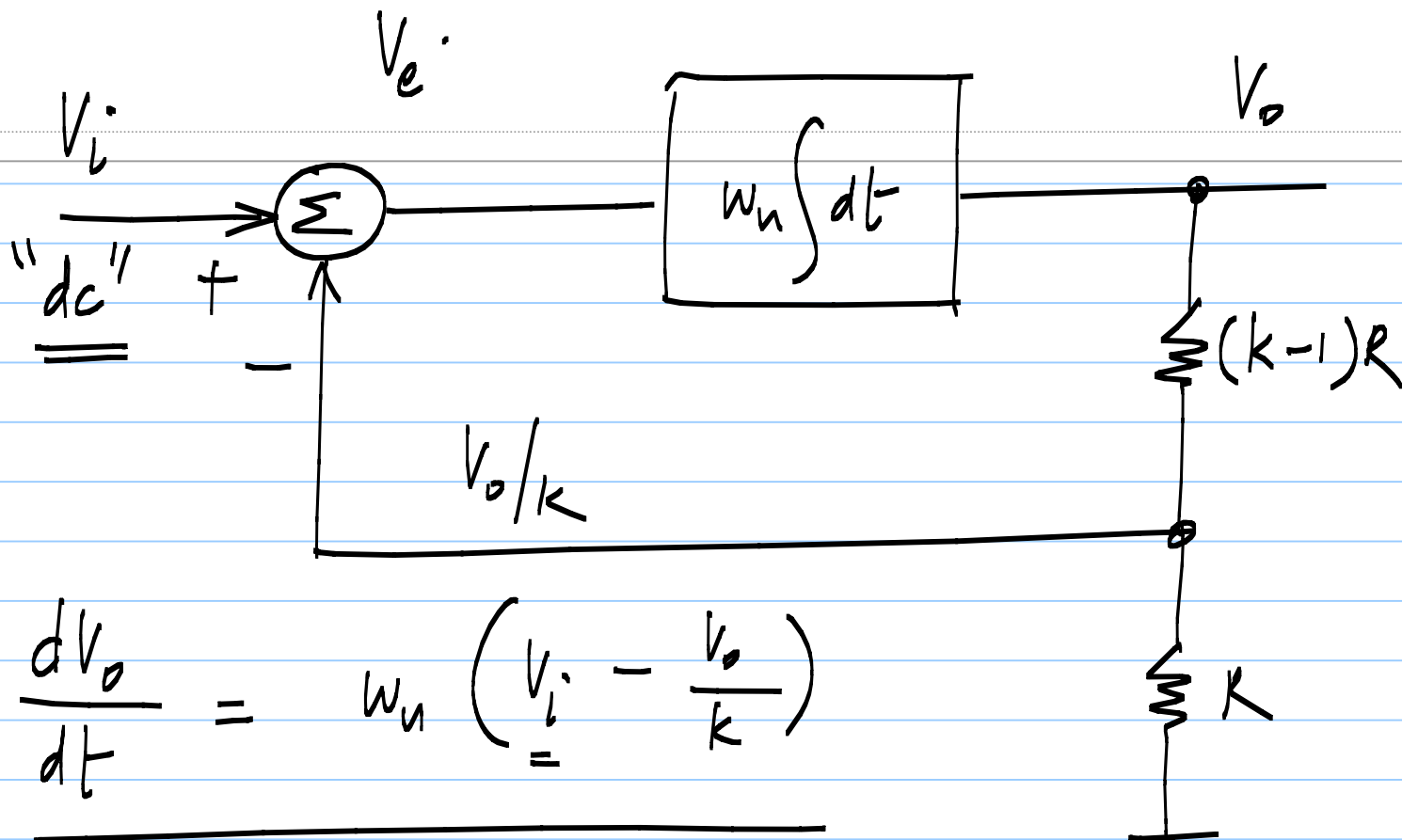
$$V_o = \omega_n \int V_e \cdot dt$$

ω_n : dimensions of frequency



$$\begin{aligned} \omega_n &= 1 \text{ Grad/s} \\ &= 10^9 \cdot \text{rad/s} \end{aligned}$$

$$\begin{aligned} \omega_n &= 4 \text{ Grad/s} \\ &= 4 \times 10^9 \text{ rad/s} \end{aligned}$$



$$\frac{dV_o}{dt} = \omega_n \left(\underline{V_i} - \frac{V_o}{k} \right)$$

$$\frac{dV_o}{V_i - \frac{V_o}{k}} = \omega_n \cdot dt \quad \xrightarrow[\substack{\text{Integrate} \\ V_i : \text{const}}]{\quad} \quad \therefore \quad \frac{dV_o}{\underline{k \cdot V_i - V_o}} = \frac{\omega_n \cdot dt}{k}$$

$$\frac{dv_o}{kV_i - v_o} = \frac{\omega_n \cdot dt}{k}$$

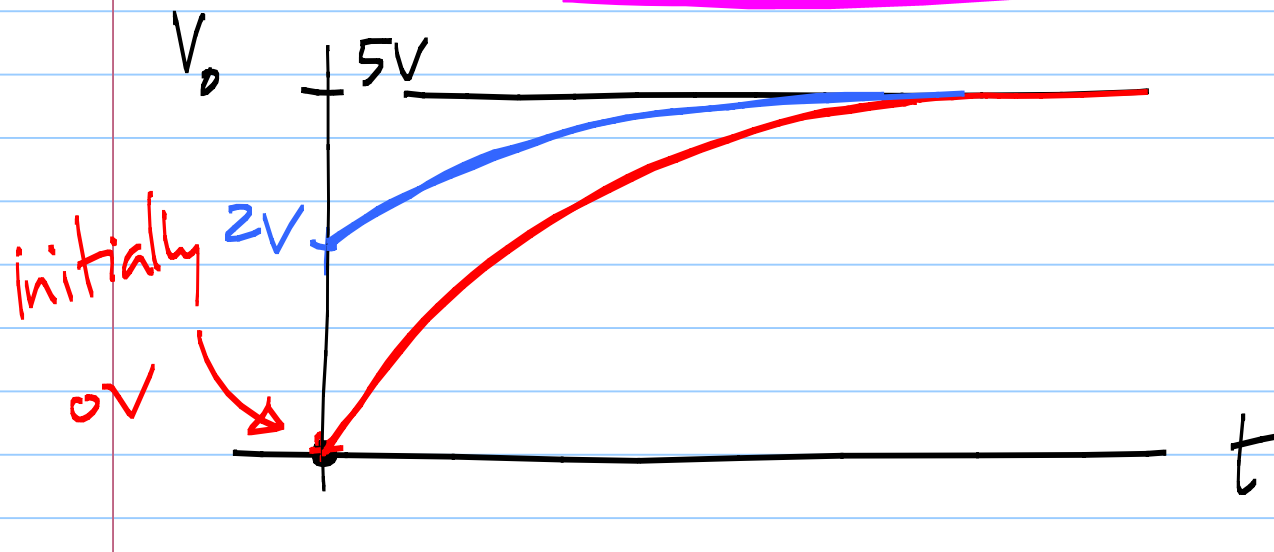
Integrating

$$-\ln(kV_i - v_o) \Big|_{v_o(0)}^{v_o(t)} = \frac{\omega_n}{k} \cdot t \Big|_0^t$$

$$\ln \frac{kV_i - v_o(t)}{kV_i - v_o(0)} = -\frac{\omega_n}{k} \cdot t$$

$$V_o(t) = V_o(0) \cdot \exp\left(-\frac{\omega_n}{k} \cdot t\right)$$

$$+ k \cdot V_i \left(1 - \exp\left(-\frac{\omega_n}{k} \cdot t\right)\right)$$



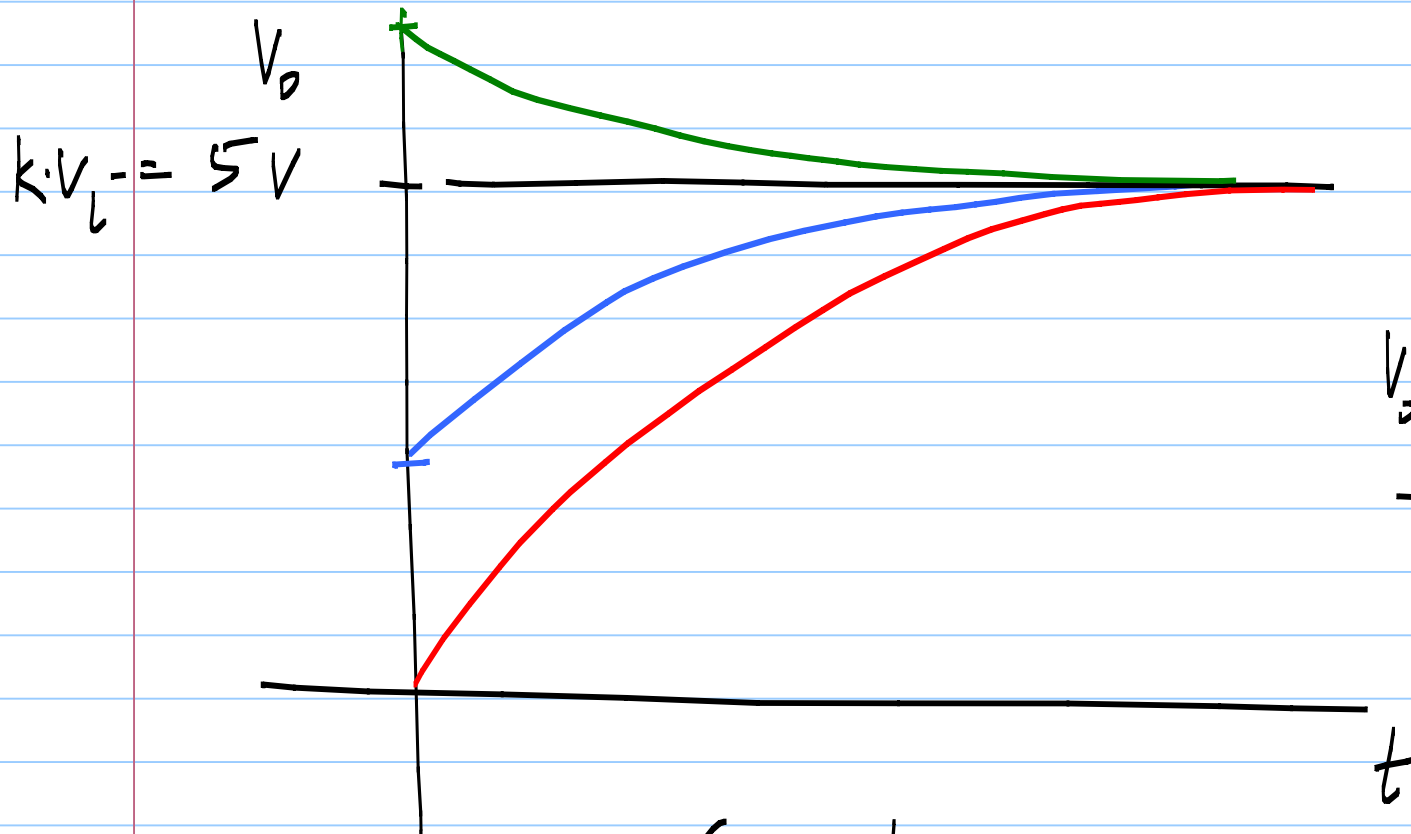
$$V_o(t) = k V_i$$

When $t = \infty$

$$V_o(t) = V_o(0) \exp\left(-\frac{\omega_n t}{k}\right) + kV_i \left(1 - \exp\left(-\frac{\omega_n t}{k}\right)\right)$$

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$$k = 5$$

$$V_i = 1V$$

$$V_o = kV_i \left(1 - \exp\left(-\frac{\omega_n t}{k}\right)\right)$$

$$= (0.99) kV_i$$

$$\exp\left(-\frac{\omega_n t}{k}\right) = 0.01 \Rightarrow t = \frac{4.6}{2 \ln(10)} \left(\frac{k}{\omega_n}\right)$$

$$\exp\left(-\frac{\omega_n}{k} t\right) = 0.01$$

$$\Rightarrow t = \frac{2 \ln(10)}{4.6} \left(\frac{k}{\omega_n}\right)$$

$$\frac{k}{\omega_n} = \frac{5}{10^9 \text{ rad/s}} = \underline{\underline{5 \text{ ns}}}$$

$$t = 23 \text{ ns} \rightarrow \underline{\underline{4.6 \text{ ns}}}$$

reaches 99% of the steady state value $k v_i$ (zero initial condition)

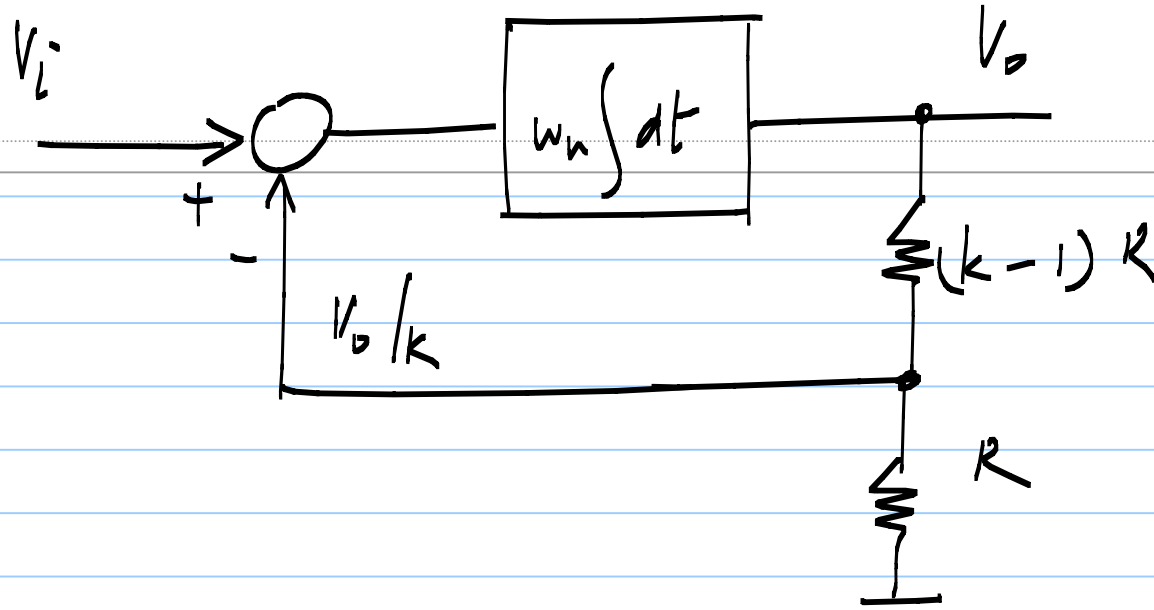
$$\omega_n = 10^9 \text{ rad/s}$$

$$k = 5$$

$$\omega_n = 5 \times 10^9 \text{ rad/s}$$

$$\frac{k}{\omega_n} = \frac{5}{5 \cdot 10^9 \text{ rad/s}} = 1 \text{ ns}$$

Note Title



$\frac{k}{w_n}$: time constant

- Compare divided output to the input & integrate the difference to drive the output

- Integrator: - w_n - speed of integration

- $V_o(t)$ $\left\langle \begin{array}{l} \text{First order DE} \\ \exp(-w_n t/k) \end{array} \right.$