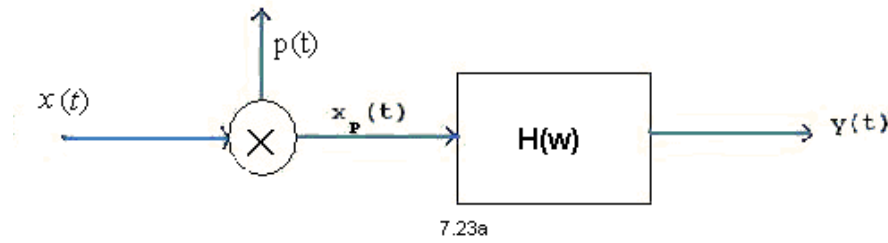


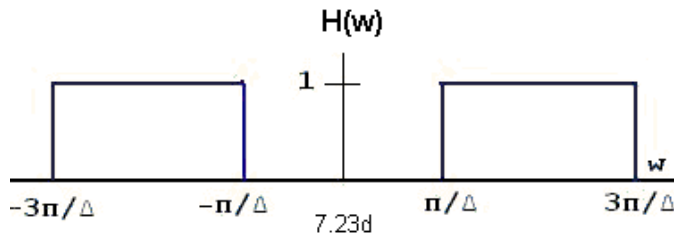
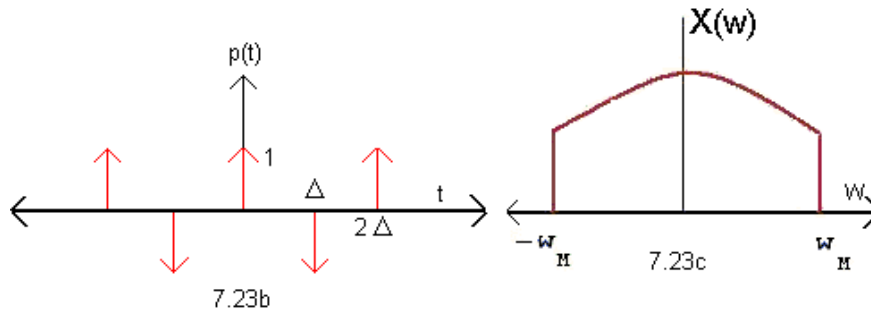
**Module 3 : Sampling and Reconstruction**  
**Problem Set 3**

**Problem 1**

Shown in figure below is a system in which the sampling signal is an impulse train with alternating sign.



The sampling signal  $p(t)$ , the Fourier Transform of the input signal  $x(t)$  and the frequency response of the filter are shown below:



- (a) For  $\Delta < \frac{\pi}{2\omega_M}$ , sketch the Fourier transform of  $x_p(t)$  and  $y(t)$ .
- (b) For  $\Delta < \frac{\pi}{2\omega_M}$ , determine a system that will recover  $x(t)$  from  $x_p(t)$  and another that will recover  $x(t)$  from  $y(t)$ .
- (c) What is the *maximum* value of  $\Delta$  in relation to  $\omega_M$  for which  $x(t)$  can be recovered from either  $x_p(t)$  or  $y(t)$ ?

**Solution 1**

(a) As  $x_p(t) = x(t) p(t)$

By dual of convolution theorem we have  $X_p(\omega) = X(\omega) P(\omega)$ .

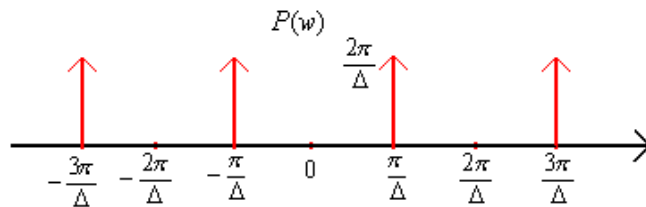
So we first find the Fourier Transform of  $p(t)$  as follows :-

The Fourier Transform of a periodic function is an impulse train at intervals of  $\omega = \frac{2\pi}{2\Delta} = \frac{\pi}{\Delta}$ .

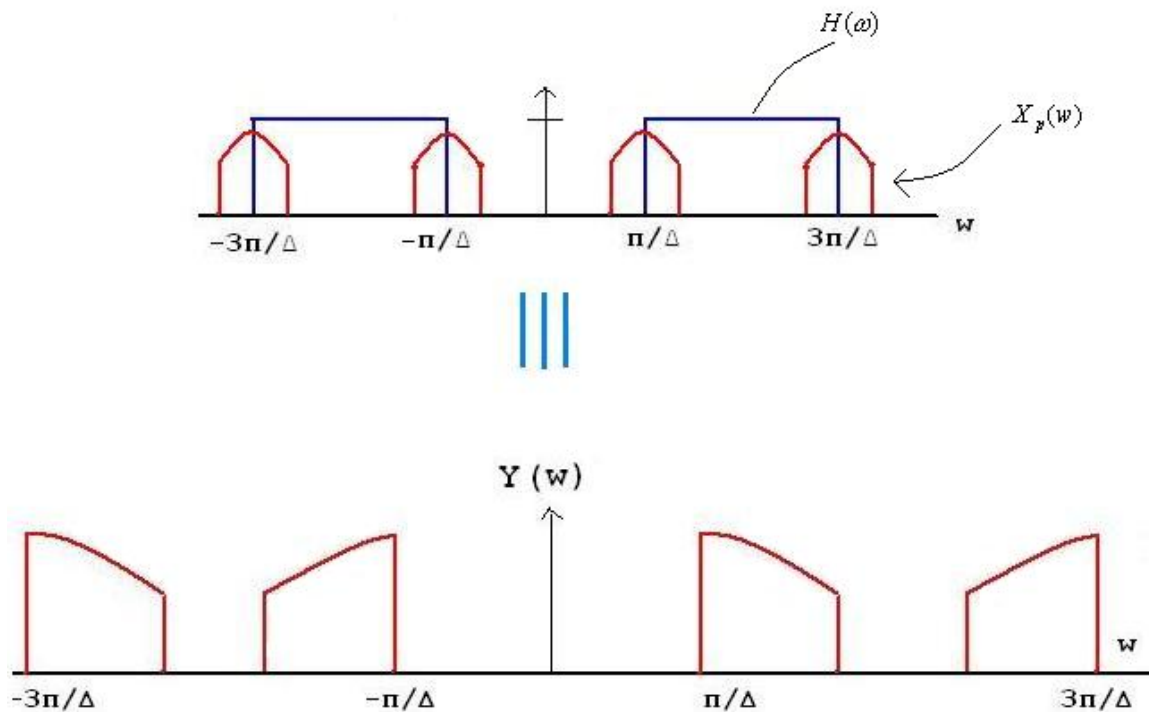
Strength of impulse at  $\frac{k\pi}{\Delta}$  being:

$$\begin{aligned}
 c_k &= \frac{\pi}{\Delta} \int_{(2\Delta)} p(t) e^{j\frac{2\pi k t}{2\Delta}} dt \\
 &= \frac{\pi}{\Delta} (1 - e^{j\frac{2\pi k}{2\Delta}\Delta}) = \frac{\pi}{\Delta} (1 - e^{j k \pi}) \\
 &= \frac{\pi}{\Delta} (1 - (-1)^k)
 \end{aligned}$$

Thus, we have can sketch  $P(\omega)$ :



Thus we can also sketch  $X_p(\omega)$  and hence  $Y(\omega)$ :



(b) To recover  $x(t)$  from  $x_p(t)$ :

Modulate  $x_p(t)$  with  $\cos(\frac{\pi}{\Delta}t)$ .

$\cos(\frac{\pi}{\Delta}t)$  has a spectrum with impulses of equal strength at  $\frac{\pi}{\Delta}$  &  $-\frac{\pi}{\Delta}$ . Thus the new signal will have copies of the original spectrum (modulated by a constant of-course) at all even multiples of  $\frac{\pi}{\Delta}$ . Now an appropriate Low-pass filter can extract the original spectrum!

**To recover  $x(t)$  from  $y(t)$ :**

Here too, notice from the figures that modulation with  $\cos(\frac{\pi}{\Delta}t)$  will do the job. Here too, the modulated signal will have copies of the original spectrum at all even multiples of  $\frac{\pi}{\Delta}$ .

(c) So long as adjacent copies of the original spectrum do not overlap in  $X_p(\omega)$ , theoretically one can reconstruct the original signal. Therefore the condition is:

$$2\omega_M < \frac{2\pi}{\Delta} \Rightarrow \Delta < \frac{\pi}{\omega_M}$$

### Problem 2

The signal  $y(t)$  is obtained by convolving signals  $x_1(t)$  and  $x_2(t)$  where:

$$|X_1(\omega)| = 0 \text{ for } |\omega| > 1000\pi \quad \&$$

$$|X_2(\omega)| = 0 \text{ for } |\omega| > 2000\pi$$

Impulse train sampling is performed on  $y(t)$  to get  $y_p(t) = \sum_{-\infty}^{\infty} y(nT)\delta(t - nT)$ .

Specify the range of values of  $T$  so that  $y(t)$  may be recovered from  $y_p(t)$ .

### Solution 2

By the Convolution Theorem,

$$Y(\omega) = X_1(\omega)X_2(\omega)$$

$$Y(\omega) = 0 \text{ for } |\omega| > 1000\pi$$

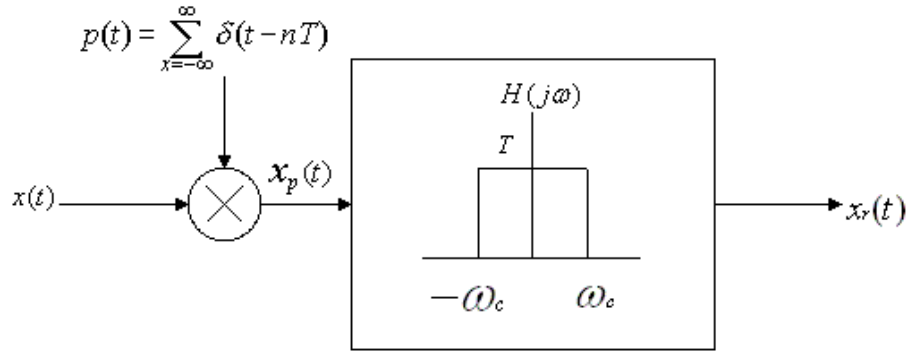
Thus from the Sampling Theorem, the sampling rate must exceed  $2 * \frac{1000\pi}{2\pi} = 1000$ .

Thus  $T$  must be less than  $10^{-3}$ , i.e: 1millisecond.

### Problem 3

In the figure below, we have a sampler, followed by an ideal low pass filter, for reconstruction of  $x(t)$  from its samples  $x_p(t)$ . From the sampling theorem, we know that if  $\omega_s = \frac{2\pi}{T}$  is greater than twice the highest frequency present in  $x(t)$  and  $\omega_c = \frac{\omega_s}{2}$ , then the reconstructed signal will exactly equal  $x(t)$ . If this condition on the bandwidth of  $x(t)$  is violated, then  $x_r(t)$  will not equal  $x(t)$ . We seek to show in this problem that if  $\omega_c = \frac{\omega_s}{2}$ , then for any choice of  $T$ ,  $x_r(t)$  and  $x(t)$  will always be equal at the sampling instants;

that is,  $x_r(kT) = x(kT)$ ,  $k = 0, \pm 1, \pm 2, \dots$



To obtain this result, consider the following equation which expresses  $x_r(t)$  in terms of the samples of  $x(t)$ :

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT) T \frac{\omega_c}{\pi} \frac{\text{Sin}[\omega_c(t - nT)]}{\omega_c(t - nT)}$$

With  $\omega_c = \frac{\omega_s}{2}$ , this becomes

$$x_r(t) = \sum_{n=-\infty}^{\infty} x(nT) \frac{\text{Sin}\left[\frac{\pi}{T}(t - nT)\right]}{\frac{\pi}{T}(t - nT)}$$

By considering the value of  $\mu$  for which  $\frac{\text{Sin}(\mu)}{\mu} = 0$ , show that, without any restrictions on  $x(t)$ ,  $x_r(kT) = x(kT)$  for any integer value of  $k$ .

### Solution 3

In order to show that  $x_r(t)$  and  $x(t)$  are equal at the sampling instants, consider

$$\lim_{t \rightarrow kT} x_r(t) = \lim_{t \rightarrow kT} \sum_{n=-\infty}^{\infty} x(nT) \frac{\text{Sin}\left[\frac{\pi}{T}(t - nT)\right]}{\frac{\pi}{T}(t - nT)} \quad (k \in \mathbb{Z})$$

$$= \sum_{n=-\infty}^{\infty} \left( \lim_{t \rightarrow kT} x(nT) \frac{\text{Sin} \left[ \frac{\pi}{T} (t - nT) \right]}{\frac{\pi}{T} (t - nT)} \right) \quad (\text{assuming limit and summation are interchangeable})$$

$$= \sum_{n=-\infty, n \neq k}^{\infty} \left( x(nT) \frac{\text{Sin} \left[ \frac{\pi}{T} (kT - nT) \right]}{\frac{\pi}{T} (kT - nT)} \right) + \lim_{t \rightarrow kT} \left( x(kT) \frac{\text{Sin} \left[ \frac{\pi}{T} (t - kT) \right]}{\frac{\pi}{T} (t - kT)} \right)$$

$$= \sum_{n=-\infty, n \neq k}^{\infty} \left( x(nT) \frac{\text{Sin} [\pi(k-n)]}{\pi(k-n)} \right) + x(kT) \lim_{t \rightarrow kT} \left( \frac{\text{Sin} \left[ \frac{\pi}{T} (t - kT) \right]}{\frac{\pi}{T} (t - kT)} \right)$$

$$= 0 + x(kT) \times 1 \left( \begin{array}{l} \because (k-n) \in Z \Leftrightarrow \text{Sin} [\pi(k-n)] = 0 \\ \text{and } \lim_{x \rightarrow 0} \frac{\text{Sin } x}{x} = 1 \end{array} \right)$$

Thus,  $\lim_{x \rightarrow kT} x_r(t) = x(kT)$

Assuming the continuity of  $x_r(t)$  at  $t = kT$ ,

$$x_r(kT) = x(kT), \quad \forall k \in Z$$

#### Problem 4

This problem deals with one procedure of bandpass sampling and reconstruction. This procedure, used when  $x(t)$  is real, consists of multiplying  $x(t)$  by a complex exponential and then sampling the product. The sampling system is shown in **fig. (a)** below. With  $x(t)$  real and with  $X(j\omega)$  nonzero only for  $\omega_1 < |\omega| < \omega_2$ , the frequency is chosen to be  $\omega_0 = \left(\frac{1}{2}\right)(\omega_2 + \omega_1)$ , and the lowpass filter

$$H_1(j\omega) \text{ has cutoff frequency } \left(\frac{1}{2}\right)(\omega_2 + \omega_1).$$

(a) For  $X(j\omega)$  shown in **fig. (b)**, sketch  $X_p(j\omega)$ .

(b) Determine the maximum sampling period  $T$  such that  $x(t)$  is recoverable from  $x_p(t)$ .

(c) Determine a system to recover  $x(t)$  from  $x_p(t)$ .

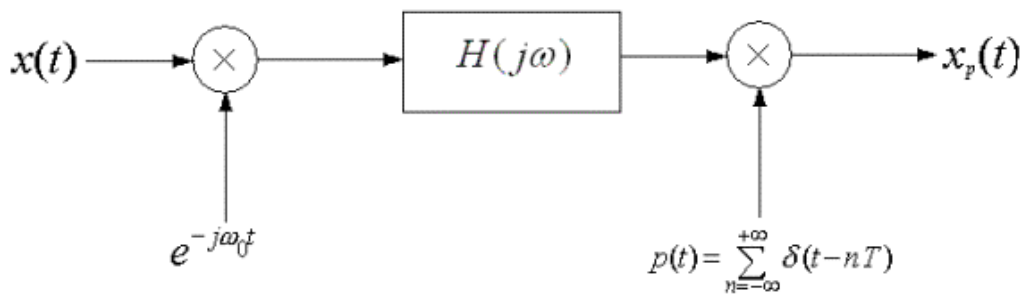


Fig. (a)

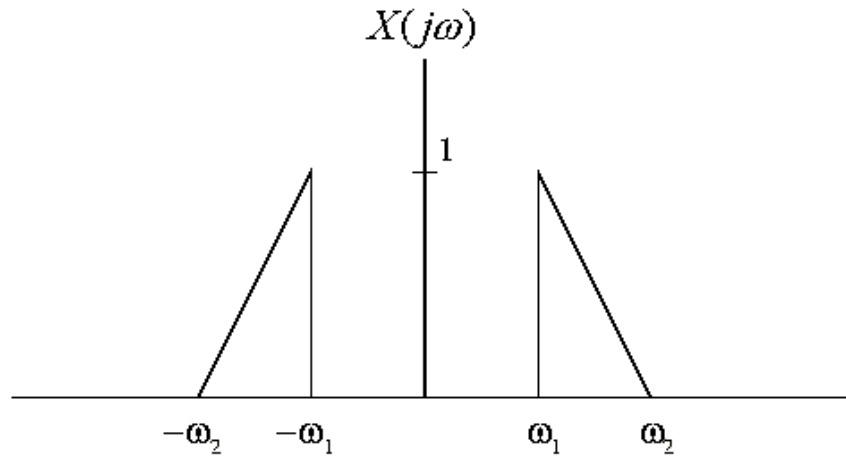
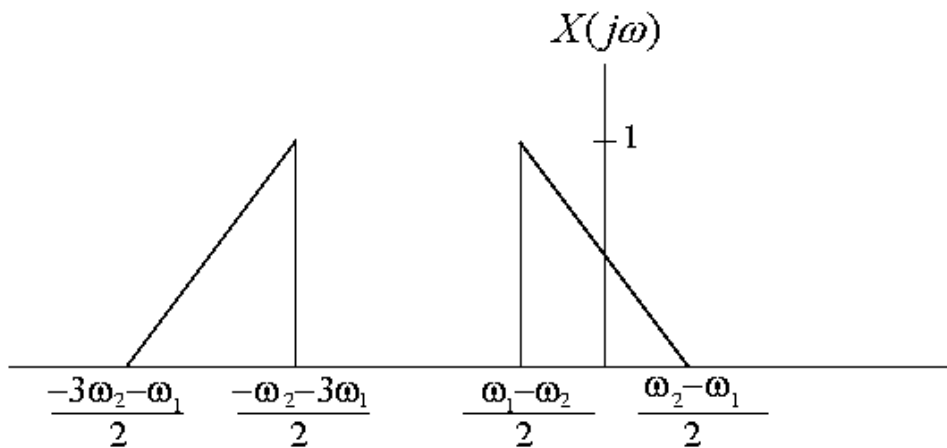


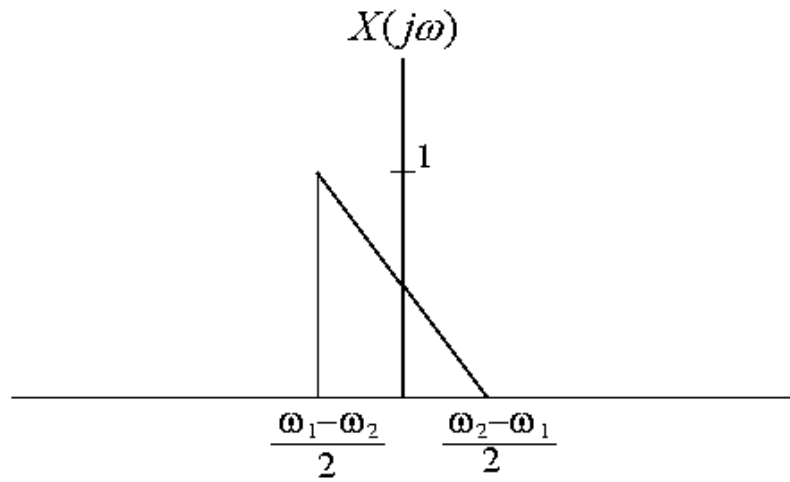
Fig. (b)

**Solution 4**

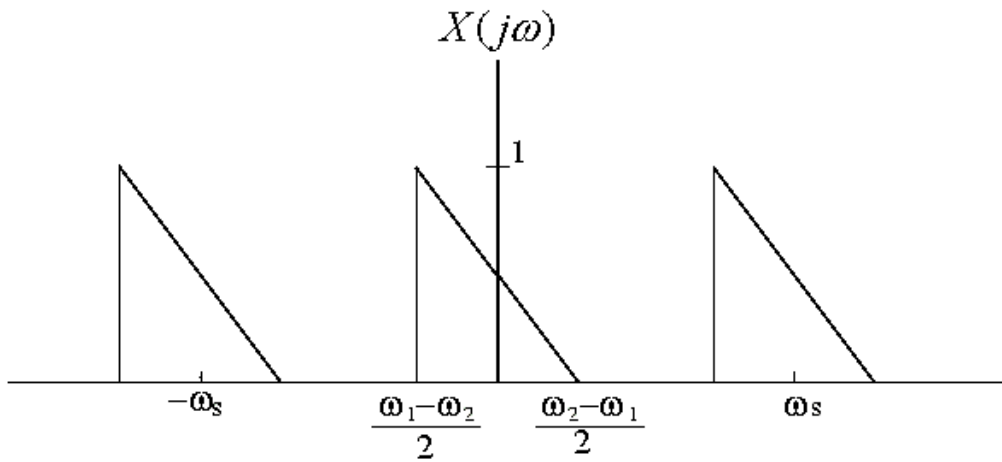
(a) Multiplication by the complex exponential  $e^{-j\omega_0 t}$  in the time domain is equivalent to shifting left the Fourier transform by an amount ' $\omega_0$ ' in the frequency domain. Therefore, the resultant transform looks as shown below:



After passing through the filter, the Fourier transform becomes:



Now sampling the signal amounts to making copies of the Fourier Transform, the center of each separated from the other by the sampling frequency in the frequency domain. Thus  $X_p(j\omega)$  has the following form (assuming that the sampling frequency is large enough to avoid overlapping between the copies):



(b)  $x(t)$  is recoverable from  $x_p(t)$  only if the copies of the Fourier Transform obtained by sampling do not overlap with each other. For this to happen, the condition set down by the Shannon-Nyquist Sampling Theorem for a band-limited signal has to be satisfied, i.e. the sampling frequency should be greater than twice the bandwidth of the original signal. Mathematically,

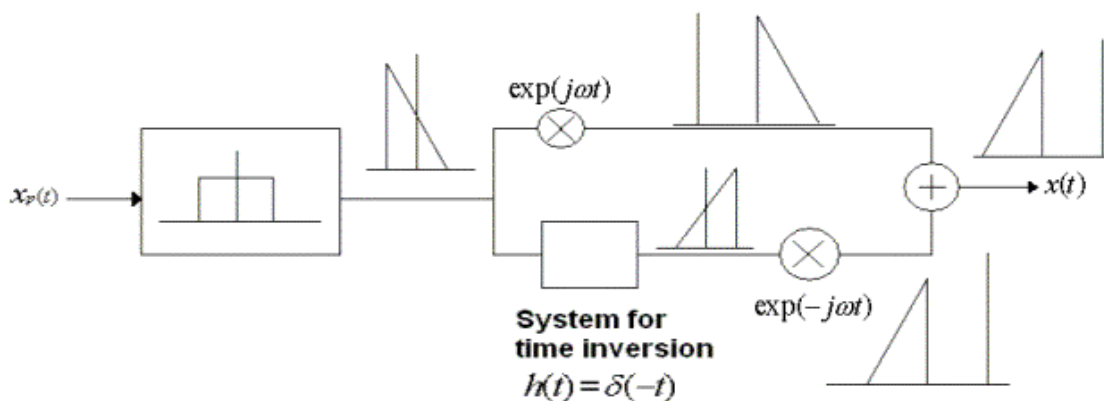
$$\omega_s > 2\omega_m$$

$$\Rightarrow \frac{2\pi}{T} > 2 \left( \frac{\omega_2 - \omega_1}{2} \right)$$

$$\Rightarrow T < \left( \frac{2\pi}{\omega_2 - \omega_1} \right)$$

Hence, the maximum sampling period for  $x(t)$  to be recoverable from  $x_p(t)$  is  $\left( \frac{2\pi}{\omega_2 - \omega_1} \right)$ .

(c) The system to recover  $x(t)$  from  $x_p(t)$  is outlined below :



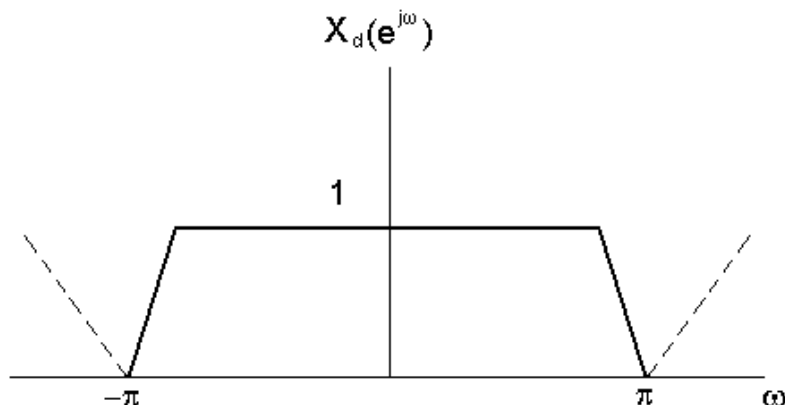
**Problem 5**

The procedure for interpolation or upsampling by an integer factor  $N$  can be thought of as the cascade of two operations. The first operation, involving system A, corresponds to inserting  $N-1$  zero-sequence values between each sequence value of  $x[n]$ , so that

$$x_p[n] = \begin{cases} x_d\left[\frac{n}{N}\right], & n = 0, \pm N, \pm 2N, \dots \\ 0, & \text{otherwise} \end{cases}$$

For exact band-limited interpolation,  $H(e^{j\omega})$  is an ideal lowpass filter.

- (a) Determine whether or not system A is linear.
- (b) Determine whether or not system A is time variant.
- (c) For  $X_d(e^{j\omega})$  as sketched in the figure and with  $N = 3$ , sketch  $X_p(e^{j\omega})$ .
- (d) For  $N = 3$ ,  $X_d(e^{j\omega})$  as in the figure, and  $H(e^{j\omega})$  appropriately chosen for exact band-limited interpolation, sketch  $X(e^{j\omega})$ .



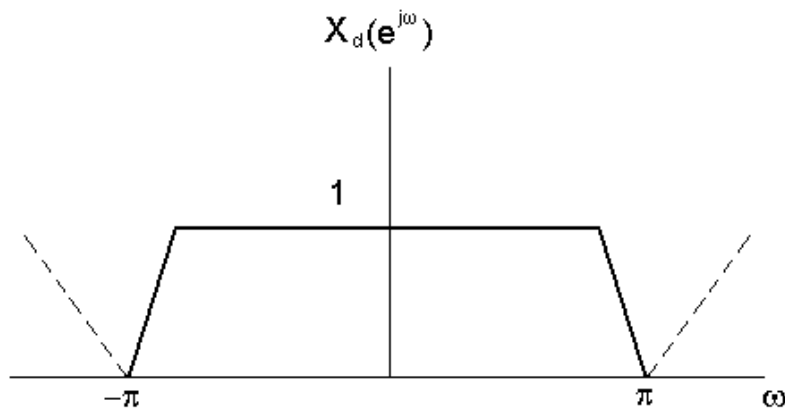


**Solution 5**

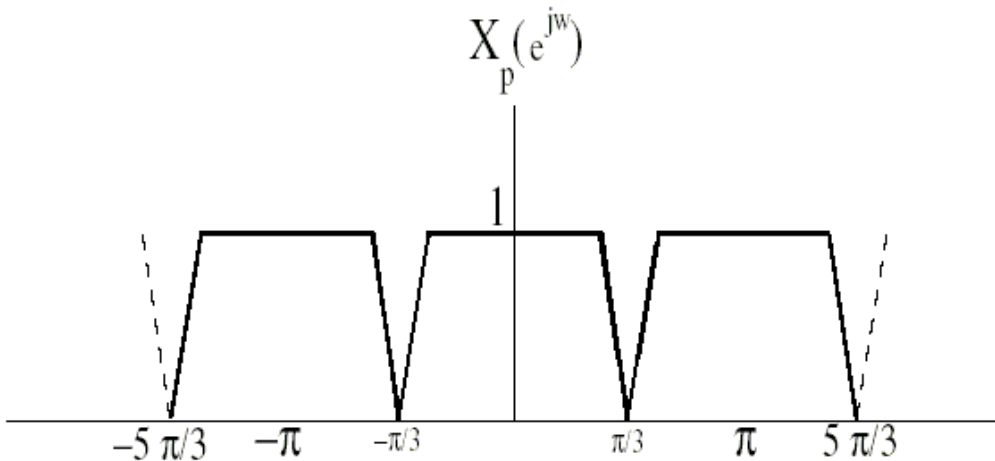
(a) Let  $x_1[n]$  and  $x_2[n]$  be two inputs with corresponding outputs  $y_1[n]$  and  $y_2[n]$  respectively. Now, suppose the new input to this system is  $\alpha x_1[n] + \beta x_2[n]$ . Then, the corresponding output is given by,  $y[n] = \alpha x_1\left[\frac{n}{N}\right] + \beta x_2\left[\frac{n}{N}\right]$  if  $n = 0, \pm N, \pm 2N, \dots$  and 0 otherwise. From this it is clear that  $y[n] = \alpha y_1[n] + \beta y_2[n]$  and hence the system is linear.

(b) The system A is not time invariant. We can see this from the following example. Let  $x[n] = 1$ , for  $n = 0, 1$  and  $x[n] = 0$  otherwise. Also assume that  $N=2$ . Thus, the output corresponding to  $x[n]$  will be  $y[n] = 1$  if  $n = 0, 2$  and  $y[n] = 0$  otherwise. Now, let  $x_1[n] = x[n-1] = 1$  if  $n = 1, 2$  and 0 otherwise. The corresponding output is  $y_1[n] = 1$  if  $n = 2, 4$  and  $y_1[n] = 0$  otherwise. Thus,  $y_1[n] = y[n-2] \neq y[n-1]$  and hence this shows that the system is not time invariant.

(c) Refer to Fig. 1 and Fig. 2

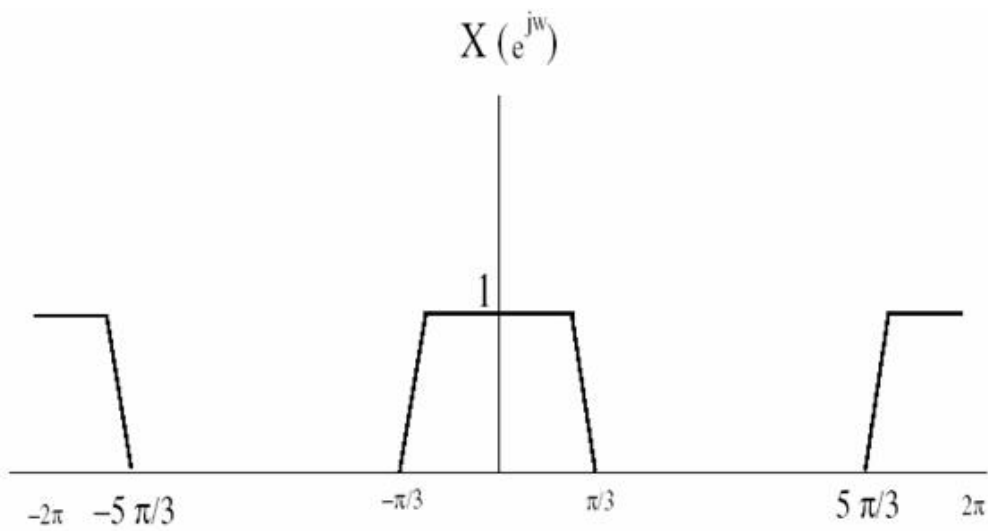


**Figure 1:** Spectrum given in the problem.



**Figure 2:** Spectrum of the interpolated signal.

(d) Refer to Fig. 3.

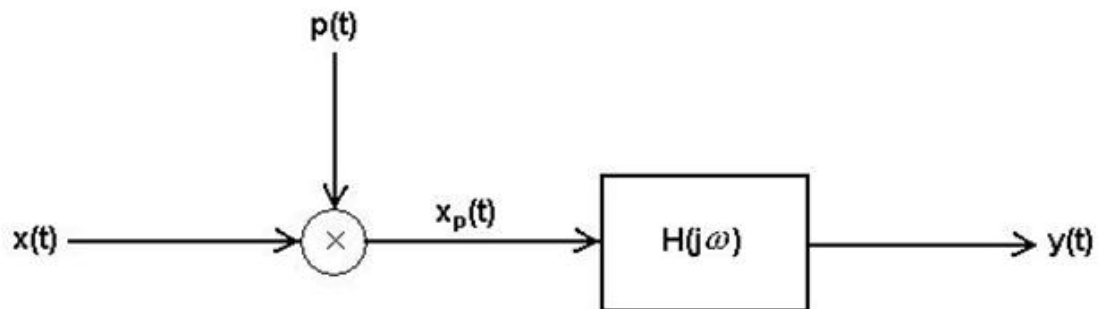


**Figure 3:** Spectrum of the upsampled signal.

**Problem 6**

Shown in the figures is a system in which the sampling signal is an impulse train with alternating sign. The Fourier Transform of the input signal is as indicated in the figures:

- (i) For  $\Delta < \pi / (2\omega_M)$ , sketch the Fourier transform of  $x_p(t)$  and  $y(t)$ .
- (ii) For  $\Delta < \pi / (2\omega_M)$ , determine a system that will recover  $x(t)$  from  $x_p(t)$ .
- (iii) For  $\Delta < \pi / (2\omega_M)$ , determine a system that will recover  $x(t)$  from  $y(t)$ .
- (iv) What is the *maximum* value of  $\Delta$  in relation to  $\omega_M$  for which  $x(t)$  can be recovered from either  $x_p(t)$  or  $y(t)$ ?



**Fig (a)**

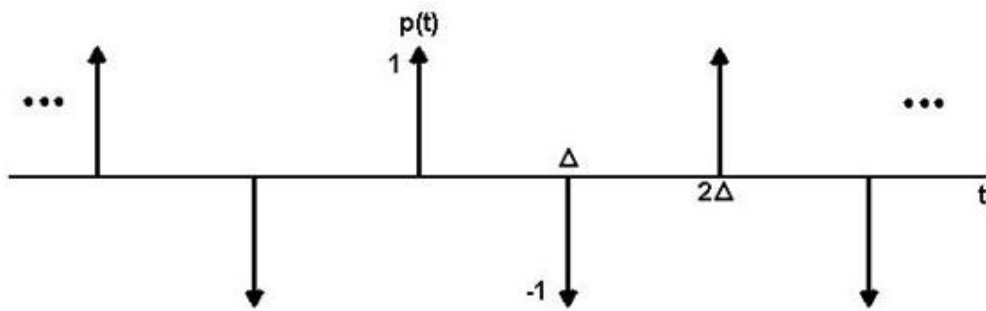


Fig (b)

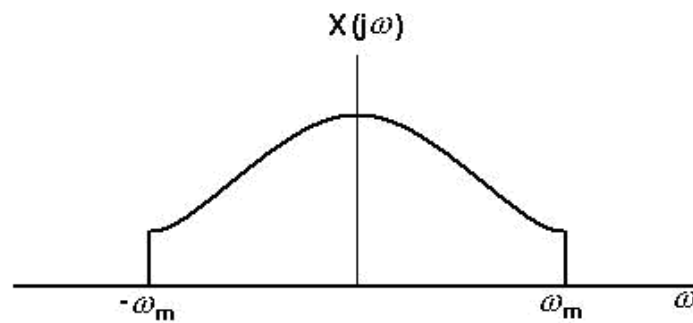


Fig (c)

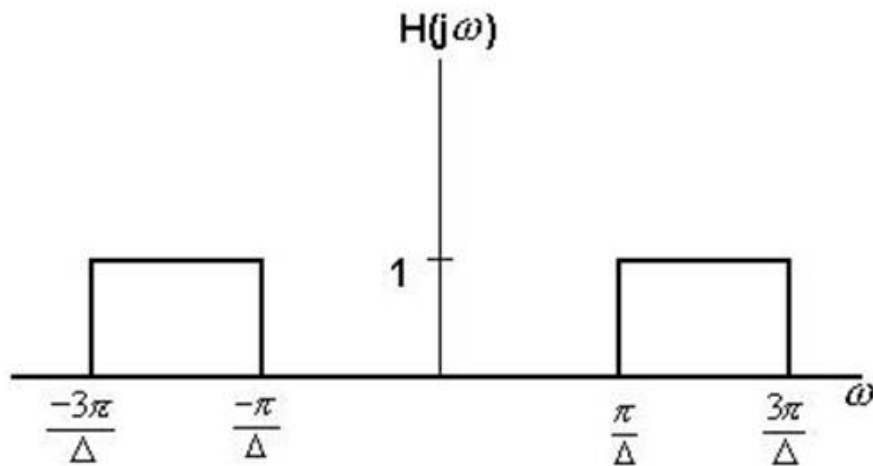


Fig (d)

### Solution 6

(a) As  $x_p(t) = x(t)p(t)$ , by dual of convolution theorem we have  $X_p(j\omega) = X(j\omega)P(j\omega)$ . So, we first find the Fourier Transform of  $p(t)$  as follows:

The Fourier Transform of a periodic function is an impulse train at intervals of  $\omega = 2\pi/2\Delta = \pi/\Delta$ , each impulse being of magnitude:

$$P(j\omega)_k = 2\pi / 2\Delta \int_{(2\Delta)} p(t) \exp(-jk\omega_j t) dt$$

$$= \pi / \Delta (1 - \cos(\pi k))$$

Here we see that the impulses on the  $\omega$  axis vanish at even values of  $k$ .

Hence, the Fourier Transform of  $X_p(j\omega)$  is as shown in **figure (a)**. In the frequency domain, the output signal  $Y$  can be found by multiplying the input with the frequency response. Hence  $Y(j\omega)$  is as shown below in the **figure (b)**.

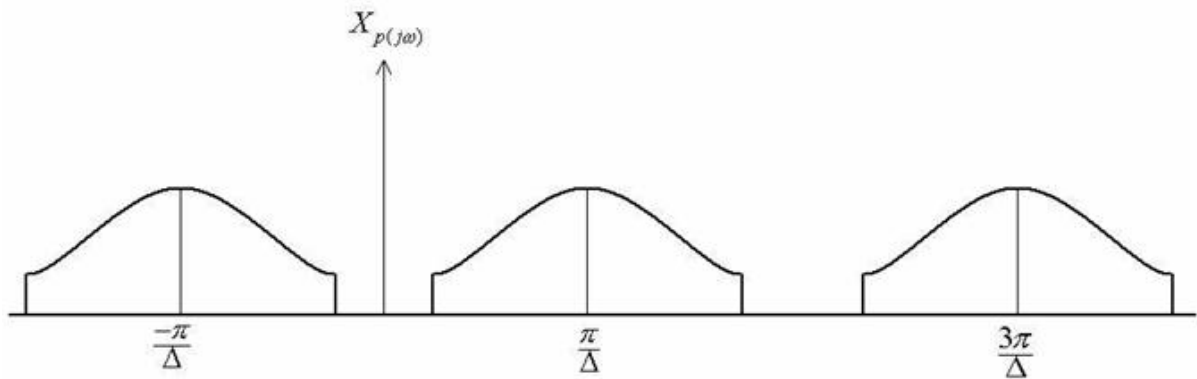


Figure (a)

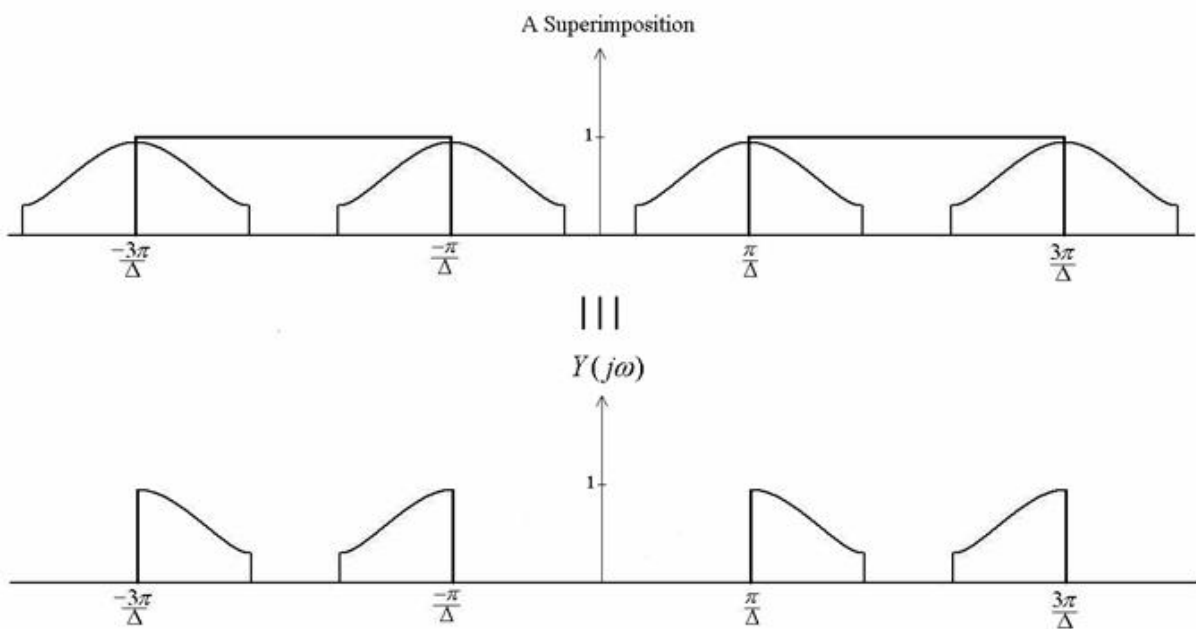


Figure (b)

**(b)** To recover  $x(t)$  from  $X_p(t)$ , we do the following two things:

- 1) Modulate the signal by

$$\cos\left(\left(2\pi/\Delta\right)t\right)$$

2) Apply a low pass filter of bandwidth  $\pi/2\Delta$ .

(c) To recover  $x(t)$  from  $y(t)$ , we do the following two things:

- 1) Modulate the signal by  $2\cos\left(\left(2\pi/\Delta\right)t\right)$ .
- 2) Apply a low pass filter of bandwidth  $\pi/2\Delta$ .

(d) Maximum value for recoverability is  $\pi/\omega_M$  as can be seen from the graphs.

### Problem 7

A signal  $x(t)$  with Fourier transform  $X(j\omega)$  undergoes impulse-train sampling to generate

$$x_p(t) = \sum_{n=-\infty}^{\infty} x(nT)\delta(t-nT),$$

where  $T = 10^{-4}$ .

For each of the following set of constraints on  $x(t)$  and/or  $X(j\omega)$ , does the sampling theorem guarantee that  $x(t)$  can be recovered exactly from  $x_p(t)$ ?

- (a)  $X(j\omega) = 0$  for  $|\omega| > 5000\pi$
- (b)  $X(j\omega) = 0$  for  $|\omega| > 15000\pi$
- (c)  $\Re\{X(j\omega)\} = 0$  for  $|\omega| > 5000\pi$
- (d)  $x(t)$  real and  $X(j\omega) = 0$  for  $\omega > 5000\pi$
- (e)  $x(t)$  real and  $X(j\omega) = 0$  for  $\omega < -15000\pi$
- (f)  $X(j\omega) * X(j\omega) = 0$  for  $|\omega| > 15000\pi$
- (g)  $|X(j\omega)| = 0$  for  $\omega > 5000\pi$

### Solution 7

From Sampling Theorem we know that if  $x(t)$  be a band-limited signal with

$X(j\omega) = 0$  for  $|\omega| > \omega_M$ , then  $x(t)$  is uniquely determined by its samples

$x(nT)$ ,  $n=0, \pm 1, \pm 2, \pm 3, \dots$ , if

$$\omega_s > 2\omega_M,$$

where

$$\omega_s = \frac{2\pi}{T}$$

Now,

$$T = 10^{-4}$$

$$\omega_s = 20000\pi$$

(a)  $X(j\omega) = 0$  for  $|\omega| > 5000\pi$

$$2\omega_M = 10000\pi$$

Here, obviously,  $\omega_s < 2\omega_M$ .

Hence  $x(t)$  can be recovered exactly from  $x_p(t)$ .

(b)  $X(j\omega) = 0$  for  $|\omega| > 15000\pi$

$$2\omega_M = 30000\pi$$

Here, obviously  $\omega_s < 2\omega_M$ ,

Hence  $x(t)$  can be recovered exactly from  $x_p(t)$ .

(c)  $\Re\{X(j\omega)\} = 0$  for  $|\omega| > 5000\pi$

Real part of  $X(j\omega) = 0$ , but we can't say anything particular about imaginary part of the  $X(j\omega)$ , thus not necessary that  $X(j\omega) = 0$  for this particular range.

Hence  $x(t)$  cannot be recovered exactly from  $x_p(t)$ .

(d)  $x(t)$  real and  $X(j\omega) = 0$  for  $\omega > 5000\pi$

As  $x(t)$  is real we have  $X(j\omega) = \overline{X(-j\omega)}$

Taking mod on both sides

$$X(j\omega) = \overline{X(-j\omega)} = 0 \text{ for } \omega > 5000\pi$$

$$\Rightarrow |\overline{X(-j\omega)}| = |X(-j\omega)| = 0 \text{ for } \omega > 5000\pi$$

$$\Rightarrow X(-j\omega) = 0 \text{ for } \omega > 5000\pi$$

$$\Rightarrow X(j\omega) = 0 \text{ for } \omega < -5000\pi$$

So, we get

$$X(j\omega) = 0 \text{ for } |\omega| > 5000\pi$$

Here, obviously  $\omega_s > 2\omega_M$ ,

Hence  $x(t)$  can be recovered exactly from  $x_p(t)$ .

(e)  $x(t)$  real and  $X(j\omega) = 0$  for  $\omega < -15000\pi$

Proceeding as above we get

$$X(j\omega) = 0 \text{ for } |\omega| > 15000\pi$$

Here, obviously  $\omega_s < 2\omega_M$ ,

Hence  $x(t)$  cannot be recovered exactly from  $x_p(t)$ .

(f)  $X(j\omega) * X(j\omega) = 0$  for  $|\omega| > 15000\pi$

When we convolve two functions with domain  $\omega_1$  to  $\omega_2$  and  $\omega_3$  to  $\omega_4$ , then the domain of their convolution function varies from  $\omega_1 + \omega_3$  to  $\omega_2 + \omega_4$ .

Here,  $\omega_1 = \omega_3$  and  $\omega_2 = \omega_4$

$$2\omega_1 = 15000$$

$$\Rightarrow \omega_1 = 7500$$

Therefore,

$$X(j\omega) = 0 \text{ for } |\omega| > 7500\pi$$

Here, obviously  $\omega_s > 2\omega_M$ .

Hence  $x(t)$  can be recovered exactly from  $x_p(t)$ .

(g)  $|X(j\omega)| = 0$  for  $\omega > 5000\pi$

We cannot say anything about  $X(j\omega)$  for  $\omega < -5000\pi$ .

Hence  $x(t)$  cannot be recovered exactly from  $x_p(t)$ .

**Problem 8**

Shown in the figures below is a system in which the input signal is multiplied by a periodic square wave. The period of  $s(t)$  is  $T$ . The input signal is band limited with

$$|X(j\omega)| = 0 \text{ for } |\omega| \geq \omega_M$$

(a) For  $\Delta = T/3$ , determine, in terms of  $\omega_M$ , the maximum value of  $T$  for which there is no aliasing among the replicas of  $X(j\omega)$  in  $W(j\omega)$ .

(b) For  $\Delta = T/4$ , determine, in terms of  $\omega_M$ , the maximum value of  $T$  for which there is no aliasing among the replicas of  $X(j\omega)$  in  $W(j\omega)$ .

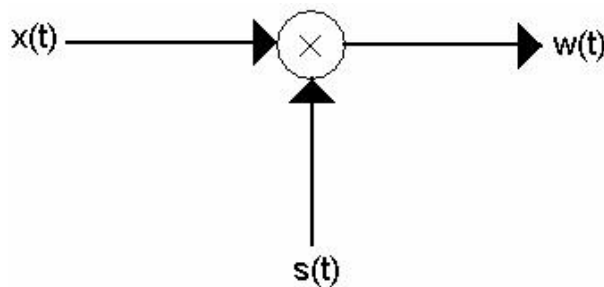


Figure (a)

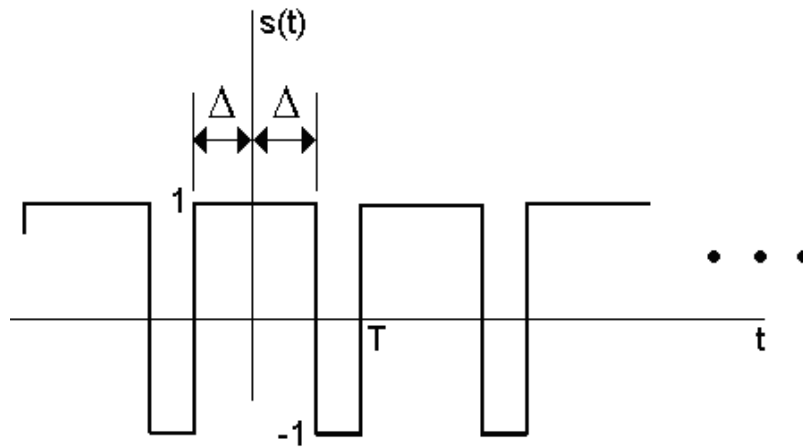


Figure (b)

**Solution 8**

(a) We know that

$$x(t) \cdot s(t) \xrightarrow{(FT)} X(j\omega) * S(j\omega)$$

$s(t)$  is a periodic square wave of period  $T$ .

With  $\Delta = T/3$  as shown in the figure.

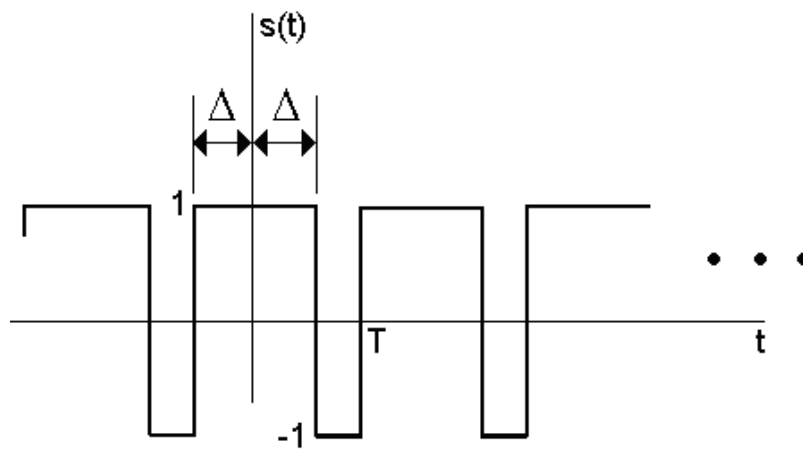


Figure (a)

We calculate  $S(j\omega)$  as follows: (FT of a periodic signal)

$$S(j\omega) = \sum a_k \delta(\omega - \omega_0)$$

where,

$$a_k = \frac{1}{T} \int_{(T)} s(t) \exp(-jk\omega_0 t) dt$$

Considering any one period  $T$ , (say from 0 to  $T$ ) and

Substituting  $\omega_0 = 2\pi / T$



$$a_k = \frac{1}{(j2\pi k)} \{1 - 2 \exp(-j4\pi k/3) + \exp(-j2\pi k)\}$$

$$= \frac{-1}{(j\pi k)} \{ \exp(-j4\pi k/3) \}$$

which can never be 0.

Thus,  $S(j\omega)$  is an impulse train situated at intervals of  $\omega_0$ .

And  $\omega_M$  has a maximum value of  $1/2(2\pi/T)$ .

$T \leq \pi / \omega_M$  (Maximum value of T without aliasing).

**(b)** We know that  
 $x(t) \cdot s(t) \rightarrow (FT) \rightarrow X(j\omega) * S(j\omega)$   
 $s(t)$  is a periodic square wave of period  $T$ .

With  $\Delta = T/4$  as shown in the figure.

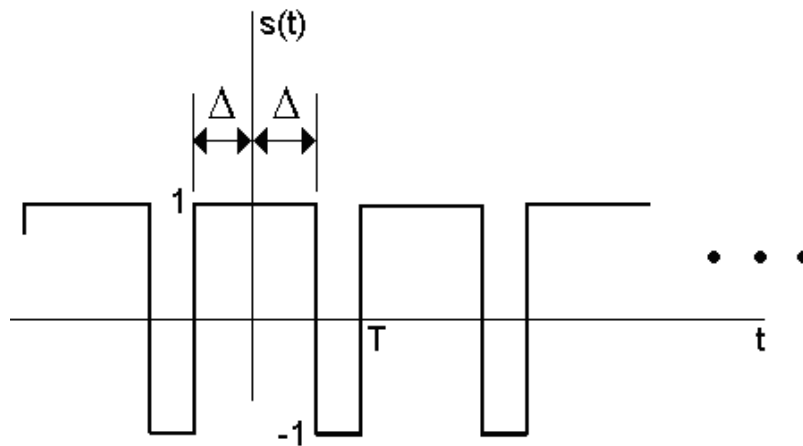


Figure (b)

We calculate  $S(j\omega)$  as follows: (FT of a periodic signal)

$$S(j\omega) = \sum a_k \delta(\omega - \omega_0)$$

where

$$a_k = \frac{1}{T} \int_{(T)} s(t) \exp(-jk\omega_0 t) dt$$

Considering any one period  $T$ , (say from 0 to T) and

Substituting  $\omega_0 = 2\pi/T$

$$a_k = \frac{1}{(j2\pi k)} \{1 - 2 \exp(-j\pi k) + \exp(-j2\pi k)\}$$

= 0 for  $k = 2m$  (i.e. k is even)

Thus,  $S(j\omega)$  is an impulse train situated at intervals of  $2\omega_0$ .

And  $\omega_M$  has a maximum value of  $1/2(2*2\pi/T)$ .

$T \leq 2\pi / \omega_M$  (Maximum value of T without aliasing).

**Problem 9 :**

**Figure I** shows the overall system for filtering a continuous-time signal using a discrete time filter. If  $X_c(j\omega)$  and  $H(\exp(j\omega))$  are as shown in **Figure II**, with  $1/T=20\text{kHz}$ , sketch  $X_p(j\omega)$ ,  $X(\exp(j\omega))$ ,  $Y(\exp(j\omega))$ ,  $Y_p(j\omega)$  and  $Y_c(j\omega)$ .

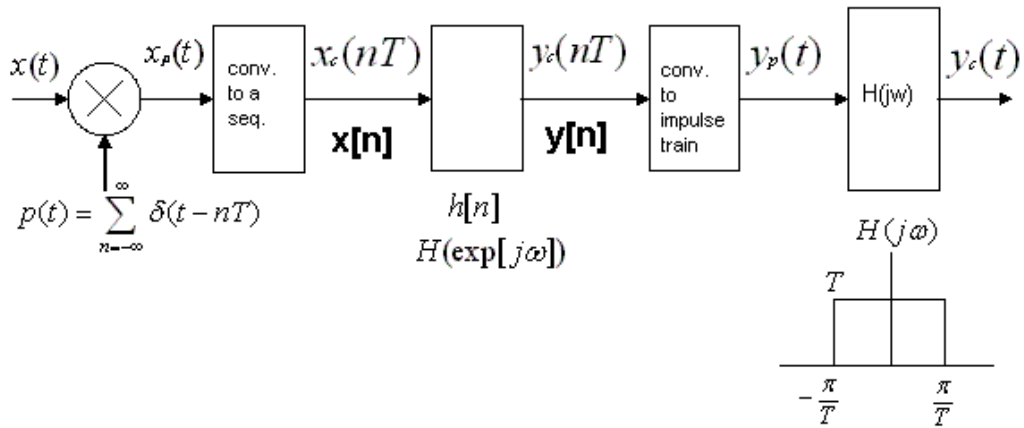


Figure ( I )

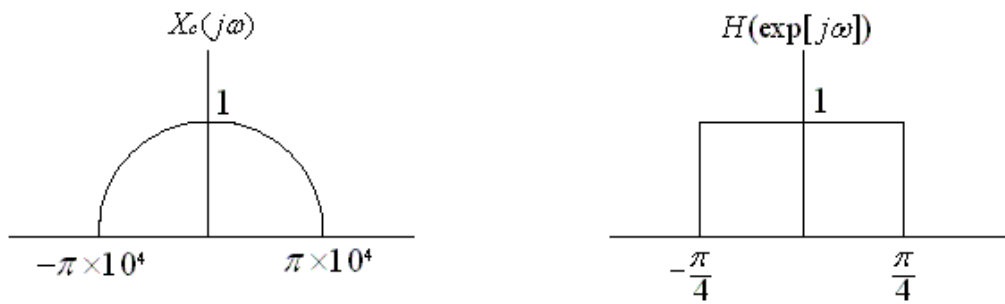
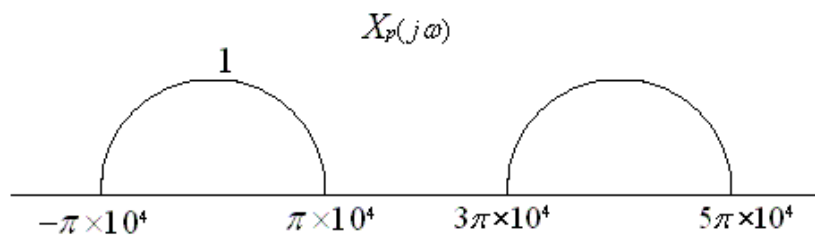
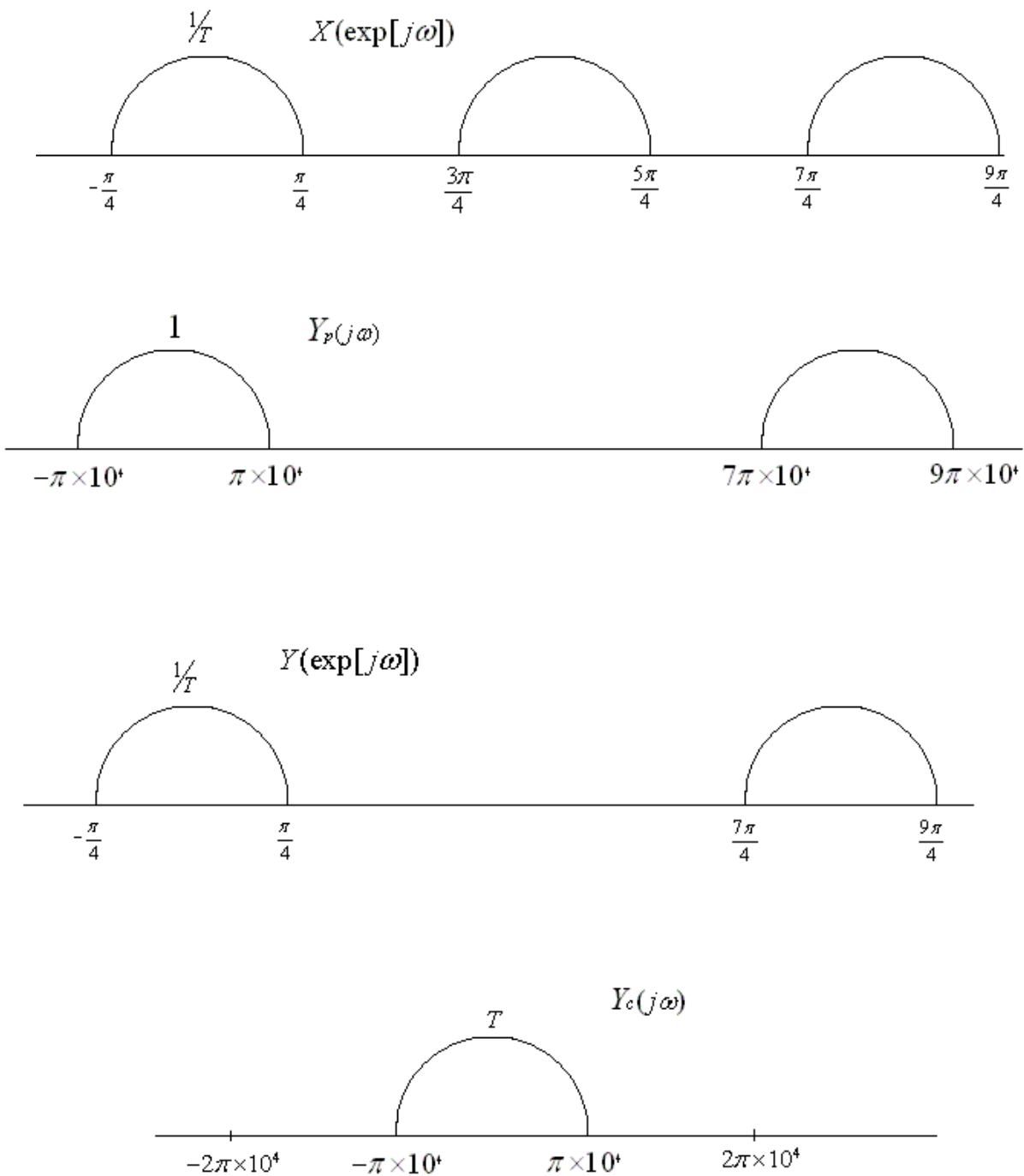


Figure ( II )

**Solution 9 :**





**Problem 10 :**

Shown in figure below is a system in which the input signal is multiplied by a periodic square wave. The period of  $s(t)$  is  $T$ . The input signal is band limited with  $|X(j\omega)| = 0$  for  $|\omega| > \omega_m$ .

- (a) For  $\Delta = T/3$  determine, in terms of  $\omega_m$ , the maximum value of  $T$  for which there is no aliasing among the replicas of  $X(j\omega)$  in  $W(j\omega)$ .
- (b) For  $\Delta = T/4$  determine, in terms of  $\omega_m$ , the maximum value of  $T$  for which there is no aliasing among the replicas of  $X(j\omega)$  in  $W(j\omega)$ .

