

Linear Programming

Other Algorithms



Introduction & Objectives

Few other methods, for solving LP problems, use an entirely different algorithmic philosophy.

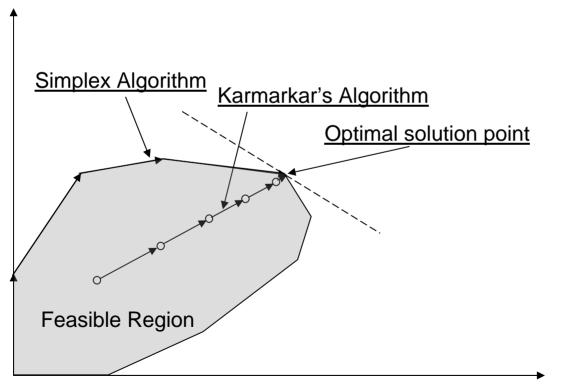
- Khatchian's ellipsoid method
- Karmarkar's projective scaling method

Objectives

- To present a comparative discussion between new methods and Simplex method
- To discuss in detail about Karmarkar's projective scaling method



Comparative discussion between new methods and Simplex method



Khatchian's ellipsoid method and Karmarkar's projective scaling method seek the optimum solution to an LP problem by moving through the interior of the feasible region.



Comparative discussion between new methods and Simplex method

1. Both *Khatchian's ellipsoid method* and *Karmarkar's projective scaling method* have been shown to be polynomial time algorithms.

Time required for an LP problem of size n is at most an^b , where a and b are two positive numbers.

 Simplex algorithm is an exponential time algorithm in solving LP problems.

Time required for an LP problem of size n is at most $c2^n$, where c is a positive number



Comparative discussion between new methods and Simplex method

- 3. For a large enough n (with positive a, b and c), $c2^n > an^b$.
 - The polynomial time algorithms are computationally superior to exponential algorithms for large LP problems.
- 4. However, the rigorous computational effort of Karmarkar's projective scaling method, is not economical for 'not-so-large' problems.



- Also known as Karmarkar's interior point LP algorithm
- Starts with a trial solution and shoots it towards the optimum solution
- LP problems should be expressed in a particular form



LP problems should be expressed in the following form:

Minimize
$$Z = \mathbf{C}^{\mathrm{T}} \mathbf{X}$$

subject to:
$$AX = 0$$

$$\mathbf{1X} = 1$$

with: $X \ge 0$

where

where
$$\mathbf{X} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \mathbf{C} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} \quad \mathbf{1} = \begin{bmatrix} 1 & 1 & \cdots & 1 \end{bmatrix}_{(1 \times n)} \quad \mathbf{A} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1n} \\ c_{21} & c_{22} & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mn} \end{bmatrix} \quad \text{and} \quad n \ge 2$$



It is also assumed that
$$\mathbf{X}_0 = \begin{bmatrix} 1/n \\ 1/n \\ \vdots \\ 1/n \end{bmatrix}$$
 is a feasible solution and $Z_{\min} = 0$. Two other variables are defined as: $r = \frac{1}{\sqrt{1-\alpha}}$ and $\alpha = \frac{(n-1)}{2}$.

Two other variables are defined as: $r = \frac{1}{\sqrt{n(n-1)}}$ and $\alpha = \frac{(n-1)}{3n}$.

Karmarkar's projective scaling method follows iterative steps to find the optimal solution



In general, kth iteration involves following computations

a) Compute $\mathbf{C}_{p} = \left[\mathbf{I} - \mathbf{P}^{\mathrm{T}} \left(\mathbf{P} \mathbf{P}^{\mathrm{T}}\right)^{-1} \mathbf{P}\right] \overline{\mathbf{C}}^{\mathrm{T}}$

where

P =
$$\begin{pmatrix} \mathbf{A}\mathbf{D}_k \\ \mathbf{1} \end{pmatrix}$$
 $\overline{\mathbf{C}} = \mathbf{C}^{\mathrm{T}}\mathbf{D}_k$ $\mathbf{D}_k = \begin{bmatrix} \mathbf{X}_k(1) & 0 & 0 & 0 \\ 0 & \mathbf{X}_k(2) & 0 & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & 0 & \mathbf{X}_k(n) \end{bmatrix}$

If $C_p = 0$, any feasible solution becomes an optimal solution. Further iteration is not required. Otherwise, go to next step.



$$\mathbf{b)} \quad \mathbf{Y}_{new} = \mathbf{X}_0 - \alpha \, r \frac{\mathbf{C}_p}{\left\|\mathbf{C}_p\right\|}$$

$$\mathbf{C)} \quad \mathbf{X}_{k+1} = \frac{\mathbf{D}_k \mathbf{Y}_{new}}{\mathbf{1} \mathbf{D}_k \mathbf{Y}_{new}}$$

However, it can be shown that for k = 0, $\frac{\mathbf{D}_k \mathbf{Y}_{new}}{1 \mathbf{D}_k \mathbf{Y}_{new}} = \mathbf{Y}_{new}$ Thus, $\mathbf{X}_1 = \mathbf{Y}_{new}$

$$\mathbf{d)} \qquad Z = \mathbf{C}^{\mathrm{T}} \mathbf{X}_{k+1}$$

e) Repeat the steps (a) through (d) by changing k as k+1



Consider the LP problem: Minimize $Z = 2x_2 - x_3$

subject to : $x_1 - 2x_2 + x_3 = 0$

 $x_1 + x_2 + x_3 = 1$

 $x_1, x_2, x_3 \ge 0$

Thus,
$$n=3$$
 $\mathbf{C} = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$ $\mathbf{A} = \begin{bmatrix} 1 & -2 & 1 \end{bmatrix}$ $\mathbf{X}_0 = \begin{bmatrix} 1/3 \\ 1/3 \\ \vdots \\ 1/3 \end{bmatrix}$

and also,
$$r = \frac{1}{\sqrt{n(n-1)}} = \frac{1}{\sqrt{3(3-1)}} = \frac{1}{\sqrt{6}}$$
 $\alpha = \frac{(n-1)}{3n} = \frac{(3-1)}{3 \times 3} = \frac{2}{9}$



Iteration 0 (k=0):

$$\mathbf{D}_0 = \begin{bmatrix} 1/3 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/3 \end{bmatrix}$$

$$\overline{\mathbf{C}} = \mathbf{C}^{\mathrm{T}} \mathbf{D}_{0} = \begin{bmatrix} 0 & 2 & -1 \end{bmatrix} \times \begin{bmatrix} 1/3 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/3 \end{bmatrix} = \begin{bmatrix} 0 & 2/3 & -1/3 \end{bmatrix}$$

$$\mathbf{AD}_0 = \begin{bmatrix} 1 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1/3 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/3 \end{bmatrix} = \begin{bmatrix} 1/3 & -2/3 & 1/3 \end{bmatrix}$$



Iteration 0 (k=0)...contd.:

$$\mathbf{P} = \begin{pmatrix} \mathbf{A}\mathbf{D}_0 \\ \mathbf{1} \end{pmatrix} = \begin{bmatrix} 1/3 & -2/3 & 1/3 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\mathbf{PP}^{\mathrm{T}} = \begin{bmatrix} 1/3 & -2/3 & 1/3 \\ 1 & 1 & 1 \end{bmatrix} \times \begin{bmatrix} 1/3 & 1 \\ -2/3 & 1 \\ 1/3 & 1 \end{bmatrix} = \begin{bmatrix} 2/3 & 0 \\ 0 & 3 \end{bmatrix}$$

$$\left(\mathbf{P}\mathbf{P}^{\mathrm{T}}\right)^{-1} = \begin{bmatrix} 1.5 & 0 \\ 0 & 1/3 \end{bmatrix}$$



Iteration 0 (k=0)...contd.:

$$\mathbf{P}^{\mathrm{T}} \left(\mathbf{P} \mathbf{P}^{\mathrm{T}} \right)^{-1} \mathbf{P} = \begin{bmatrix} 0.5 & 0 & 0.5 \\ 0 & 1 & 0 \\ 0.5 & 0 & 0.5 \end{bmatrix}$$

$$\mathbf{C}_{p} = \left[\mathbf{I} - \mathbf{P}^{\mathrm{T}} \left(\mathbf{P} \mathbf{P}^{\mathrm{T}}\right)^{-1} \mathbf{P}\right] \overline{\mathbf{C}}^{\mathrm{T}} = \begin{bmatrix} 1/6 \\ 0 \\ -1/6 \end{bmatrix}$$

$$\|\mathbf{C}_p\| = \sqrt{(1/6)^2 + 0 + (1/6)^2} = \frac{\sqrt{2}}{6}$$



Iteration 0 (k=0)...contd.:

$$\mathbf{Y}_{new} = \mathbf{X}_{0} - \alpha \, r \frac{\mathbf{C}_{p}}{\|\mathbf{C}_{p}\|} = \begin{bmatrix} 1/3 \\ 1/3 \\ \vdots \\ 1/3 \end{bmatrix} - \frac{\frac{2}{9} \times \frac{1}{\sqrt{6}}}{\frac{\sqrt{2}}{6}} \times \begin{bmatrix} 1/6 \\ 0 \\ -1/6 \end{bmatrix} = \begin{bmatrix} 0.2692 \\ 0.3333 \\ 0.3974 \end{bmatrix}$$

$$\mathbf{X}_{1} = \mathbf{Y}_{new} = \begin{bmatrix} 0.2692 \\ 0.3333 \\ 0.3974 \end{bmatrix} \qquad Z = \mathbf{C}^{\mathsf{T}} \mathbf{X}_{1} = \begin{bmatrix} 0 & 2 & -1 \end{bmatrix} \times \begin{bmatrix} 0.2692 \\ 0.3333 \\ 0.3974 \end{bmatrix} = 0.2692$$



Iteration 1 (k=1):
$$\mathbf{D}_{1} = \begin{bmatrix} 0.2692 & 0 & 0 \\ 0 & 0.3333 & 0 \\ 0 & 0 & 0.3974 \end{bmatrix}$$

$$\overline{\mathbf{C}} = \mathbf{C}^{\mathrm{T}} \mathbf{D}_{1} = \begin{bmatrix} 0 & 2 & -1 \end{bmatrix} \times \begin{bmatrix} 0.2692 & 0 & 0 \\ 0 & 0.3333 & 0 \\ 0 & 0 & 0.3974 \end{bmatrix} = \begin{bmatrix} 0 & 0.6667 & -0.3974 \end{bmatrix}$$

$$\mathbf{AD}_{1} = \begin{bmatrix} 1 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 0.2692 & 0 & 0 \\ 0 & 0.3333 & 0 \\ 0 & 0 & 0.3974 \end{bmatrix} = \begin{bmatrix} 0.2692 & -0.6666 & 0.3974 \end{bmatrix}$$



Iteration 1 (k=1)...contd.:

$$\mathbf{P} = \begin{pmatrix} \mathbf{A}\mathbf{D}_1 \\ \mathbf{1} \end{pmatrix} = \begin{bmatrix} 0.2692 & -0.6667 & 0.3974 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\mathbf{P}\mathbf{P}^{\mathrm{T}} = \begin{bmatrix} 0.2692 & -0.6667 & 0.3974 \\ 1 & 1 & 1 \end{bmatrix} \times \begin{bmatrix} 0.2692 & 1 \\ -0.6667 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\mathbf{P}^{\mathrm{T}} \begin{pmatrix} \mathbf{P}\mathbf{P}^{\mathrm{T}} \end{pmatrix}^{-1} \mathbf{P} = \begin{bmatrix} 0.441 & 0.067 & 0.492.3974 & 1 \end{bmatrix} = \begin{bmatrix} 0.675 & 0 \\ 0 & 3 \end{bmatrix}$$

$$0.492 & -0.059 & 0.567 \end{bmatrix}$$



Iteration 1 (k=1)...contd.:

$$\mathbf{C}_{p} = \left[\mathbf{I} - \mathbf{P}^{\mathrm{T}} \left(\mathbf{P} \mathbf{P}^{\mathrm{T}}\right)^{-1} \mathbf{P}\right] \overline{\mathbf{C}}^{\mathrm{T}} = \begin{bmatrix} 0.151 \\ -0.018 \\ -0.132 \end{bmatrix}$$

$$\|\mathbf{C}_p\| = \sqrt{(0.151)^2 + (-0.018)^2 + (-0.132)^2} = 0.2014$$

$$\mathbf{Y}_{new} = \mathbf{X}_{0} - \alpha \, r \frac{\mathbf{C}_{p}}{\|\mathbf{C}_{p}\|} = \begin{bmatrix} 1/3 \\ 1/3 \\ \vdots \\ 1/3 \end{bmatrix} - \frac{\frac{2}{9} \times \frac{1}{\sqrt{6}}}{0.2014} \times \begin{bmatrix} 0.151 \\ -0.018 \\ -0.132 \end{bmatrix} = \begin{bmatrix} 0.2653 \\ 0.3414 \\ 0.3928 \end{bmatrix}$$



Iteration 1 (k=1)...contd.:

$$\mathbf{D}_{1}\mathbf{Y}_{new} = \begin{bmatrix} 0.2692 & 0 & 0 \\ 0 & 0.3333 & 0 \\ 0 & 0 & 0.3974 \end{bmatrix} \times \begin{bmatrix} 0.2653 \\ 0.3414 \\ 0.3928 \end{bmatrix} = \begin{bmatrix} 0.0714 \\ 0.1138 \\ 0.1561 \end{bmatrix}$$

$$\mathbf{1D}_{1}\mathbf{Y}_{new} = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \times \begin{bmatrix} 0.0714 \\ 0.1138 \\ 0.1561 \end{bmatrix} = 0.3413$$



Iteration 1 (k=1)...contd.:

$$\mathbf{X}_{2} = \frac{\mathbf{D}_{1} \mathbf{Y}_{new}}{\mathbf{1} \mathbf{D}_{1} \mathbf{Y}_{new}} = \frac{1}{0.3413} \times \begin{bmatrix} 0.0714 \\ 0.1138 \\ 0.1561 \end{bmatrix} = \begin{bmatrix} 0.2092 \\ 0.3334 \\ 0.4574 \end{bmatrix}$$

$$Z = \mathbf{C}^{\mathrm{T}} \mathbf{X}_{2} = \begin{bmatrix} 0 & 2 & -1 \end{bmatrix} \times \begin{bmatrix} 0.2092 \\ 0.3334 \\ 0.4574 \end{bmatrix} = 0.2094$$

Two successive iterations are shown. Similar iterations can be followed to get the final solution upto some predefined tolerance level



Thank You