

Tubular Reactors heated/cooled from wall.

$$v C_p \frac{dT}{dv} = \sum_{L=1}^P r_i (-\Delta H_i^*) + q - \cancel{W_s^*}$$

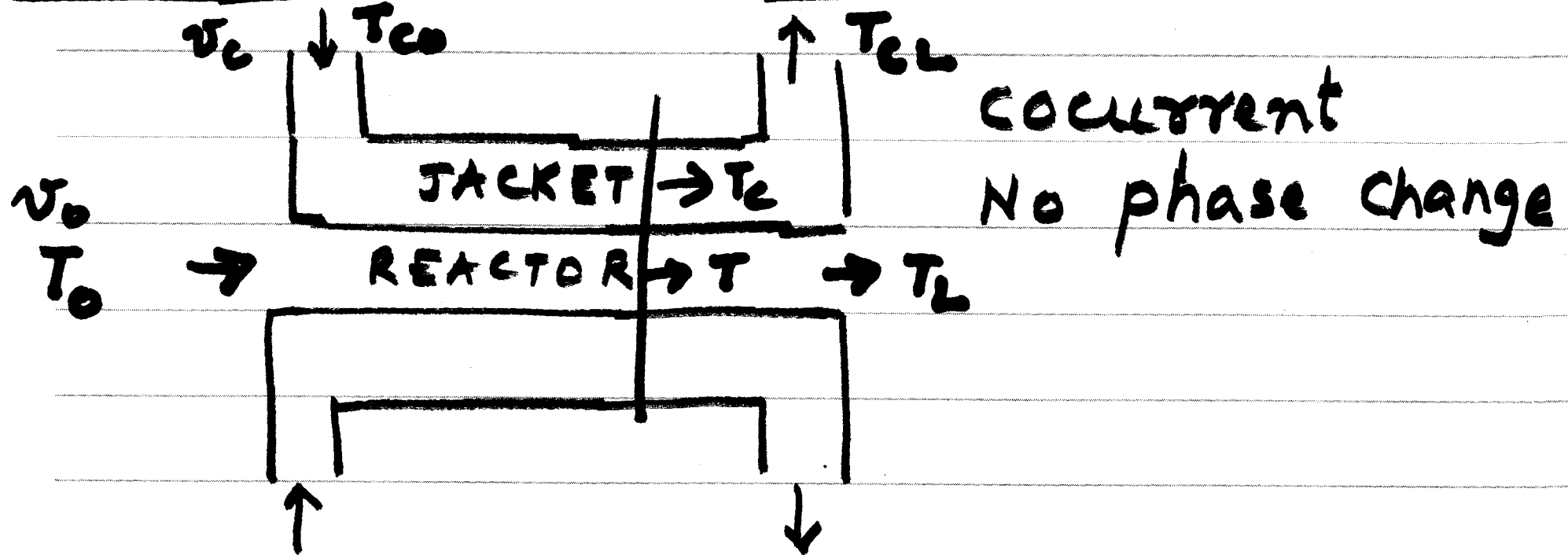
$$= \sum r_i (-\Delta H_i^*) + \frac{4h}{D} (T_c - T)$$

$$\frac{T_c}{T}$$

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9 Nov 12

Tubular Reactor heated or cooled from Wall

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$$\frac{dx_j}{dv} = f_j(x_1, \dots, x_r, T) \quad (r \text{ equations}) - (1)$$

$$v G_p \frac{dT}{dv} = \sum_{i=1}^p (-\Delta H_i^*) R_i(x_1, x_2, \dots, x_r, T) + \frac{4h}{D} (T_c - T) \dots (2)$$

Overall balance (no phase change)

38 → 3

$$\begin{aligned} \dot{V}_0 C_p (T_0 - T_R) + \dot{V}_c C_{pc} (T_{c0} - T_R) \\ + \sum_{i=1}^r F_{A0} X_i (-\Delta H_i^*) = \dot{V}_0 C_p (T - T_R) \\ + \dot{V}_c C_{pc} (T_c - T_R) \quad \text{--- (3)} \end{aligned}$$

where $F_{A0} X_i$ is the mol/s of i independent reaction ~~is~~ and so $\sum_{i=1}^r F_{A0} X_i (-\Delta H_i^*)$ is the heat absorbed or released per unit time

Substituting From (3)

$$T_c = \frac{T_{c0} + \dot{V}_0 C_p (T_0 - T) + \sum_{i=1}^r F_{A0} X_i (-\Delta H_i^*)}{\dot{V}_c C_{pc}} \quad \text{--- (4)}$$

So the differential eqn governing are (34) ~~25~~ 4

$$\frac{dx_j}{dv} = f_j(x_1, x_2, \dots, x_r, T) \quad \rightarrow \underline{\hspace{2cm}}$$

$$v C_p \frac{dT}{dv} = \frac{4h \cdot (T_c - T)}{D} + \sum_{L=1}^P (-\Delta H_L^*) x_L(x_1, x_2, \dots, x_r, T)$$

$$T_c = T_{c0} + v_0 C_p (T_0 - T) + \sum_{L=1}^r F_{A0} x_L (-\Delta H_L^*)$$

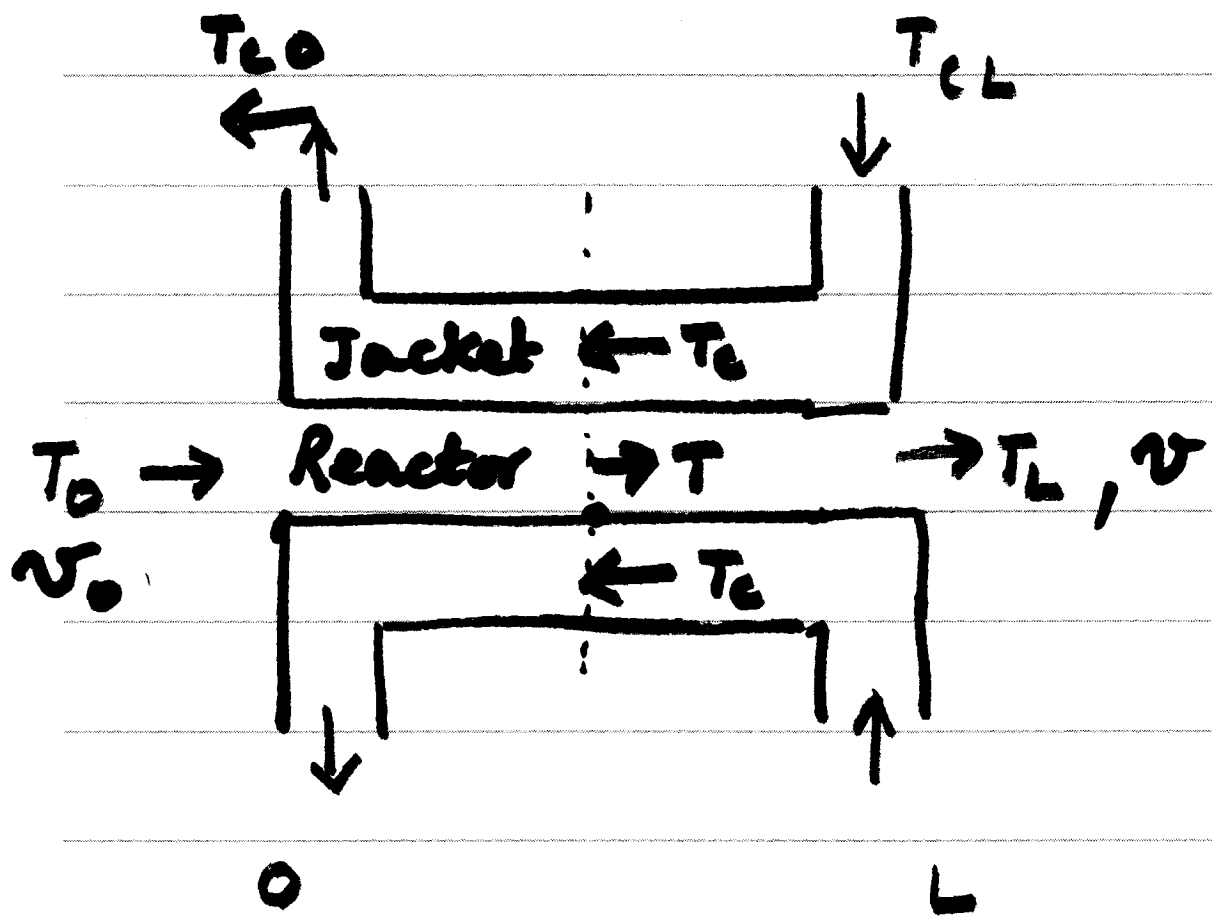
$$\left. \begin{array}{l} x_1, \dots, x_r = 0 \quad @ \quad v=0 \\ T = T_0 \quad @ \quad v=0 \\ T_c = T_{c0} \quad @ \quad v=0 \end{array} \right\}$$

$v_0 C_{pc}$

So Equations can be integrated by a forward Marching Routine

Tubular Reactors heated/cooled from Wall ③/⑥ 5

Countercurrent Flow



p rxns

$$v C_p \frac{dT}{dv} = \sum_{L=1}^p r_L (-\Delta H_L^*) + \frac{4h}{D} (T_c - T) \quad - (1)$$

(27) 6

$$\frac{dx_j}{dv} = f_j(x_1, \dots, x_r, T) \quad \dots r \text{ equations} \quad - (2)$$

overall balance between '0' at any position

$$v_0 C_p (T_0 - T_R) + v_c C_{pc} (T_c - T_R) + \sum_{L=1}^p F_{A0} x_L (-\Delta H_L^*)$$

$$= v_c C_{pc} (T_{c0} - T_R) + v C_p (T - T_R) \quad - (3)$$

$$T_c = T_{c0} + v C_p (T - T_0) - \sum_{L=1}^r F_{A0} X_j (-\Delta H_j^*) \quad \text{--- (4)}$$

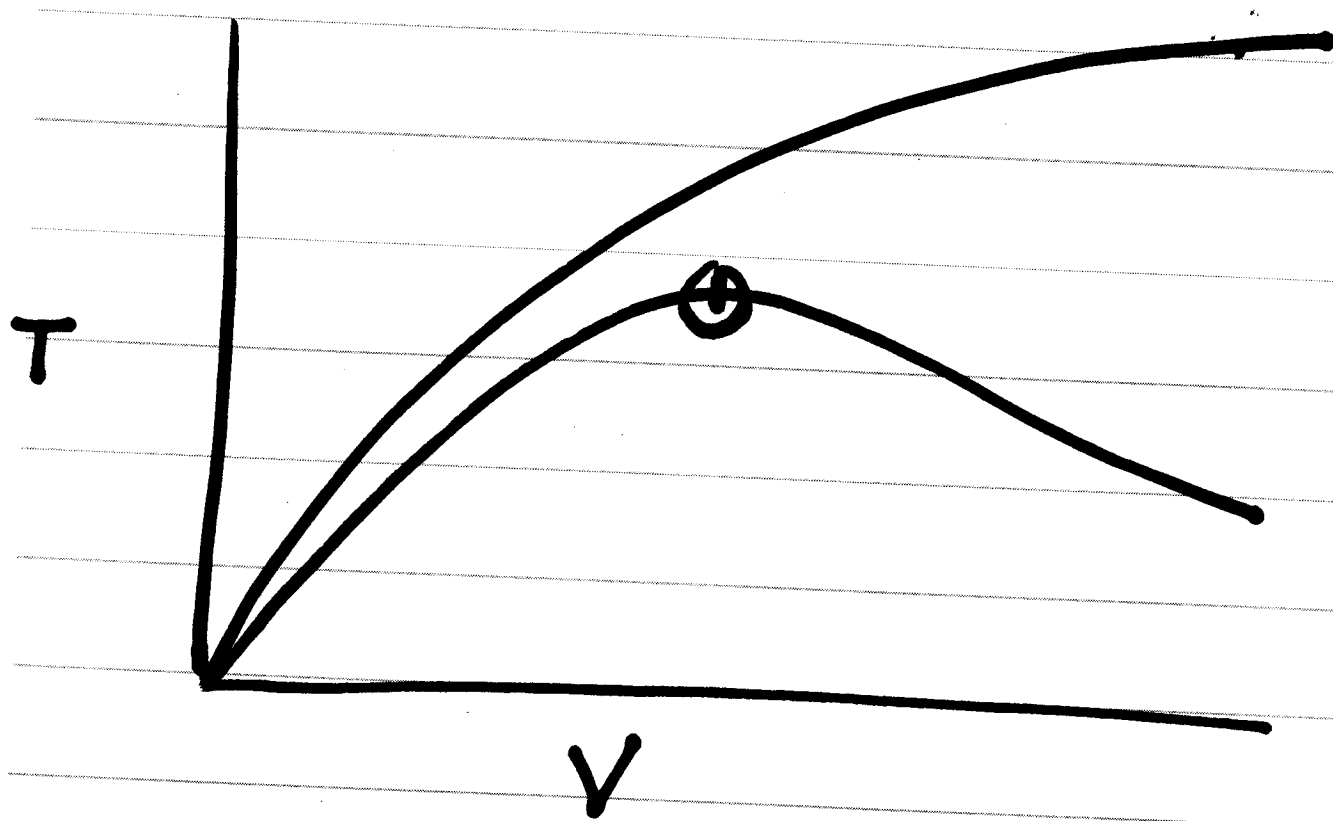
(38) ?

$v_c C_{pc}$

overall balance between 0 + L

$$v C_p (T_0 - T_R) + v_c C_{pc} (T_{cL} - T_R) + \sum_{L=1}^r F_{A0} X_j (L) (-\Delta H_j^*)$$

$$= v C_p (T_L - T_R) + v_c C_{pc} (\underline{T_{c0}} - T_R) \quad \dots (5)$$



exo.

SOLUTION PROCEDURE

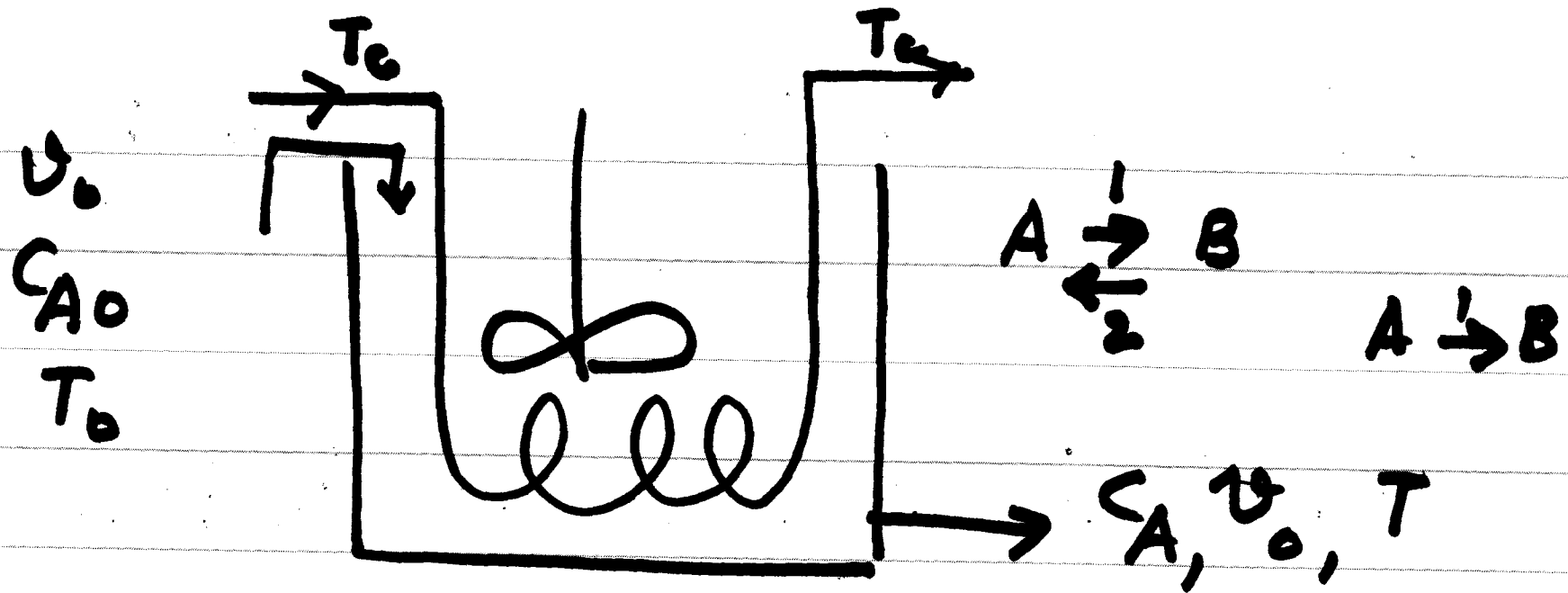
(39)⁹

- 1) Assume T_{c0}
- 2) Replace T_c in Eqn (1) from Eqn (4)
- 3) Now Eqn (1) and (2) RHS is fully specified
Since T_c at $z=0$, X_j (at $z=0$, T at $z=0$
are all specified. So Eqn (1) and (2)
can be integrated by forward march Runge
Kutta. The integration gives T, T_c, X_j (for all r
eqns). for all $z=0$ to L .
- 4) Using T (at $z=L$) check if Eqn (5) is satisfied.
Else repeat with new value of T_{c0} till Eqn (5) is

Advanced Reaction Engineering

Transient Behavior of Exothermic

Reactions in CSTR



$$F_{A0} - F_A + r_A V = \frac{dN_A}{dt} \quad - (1)$$

Let us define a variable $x = \frac{C_{A0} - C_A}{C_{A0}}$

Note x has meaning of Conversion only at steady state. Under unsteady state its just a variable

$$v_0 C_{A0} - v C_A - r_1 \left(\frac{V}{v_0} \right) = \left(\frac{V}{v_0} \right) \frac{dC_A}{dt} \quad A \rightarrow B$$

Note $r_A = (-1) r_1$; $v = \text{constant}$ assumed

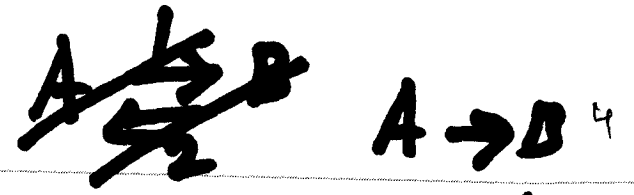
$v = v_0$ assumed so that;

$$-\tau \frac{dx}{dt} = x - \frac{r_1 \tau}{C_{A0}}$$

$$\tau \frac{dx}{dt} = -x + \frac{r_1 \tau}{C_{A0}} \quad (1)$$

where $\tau = V/v_0$

Energy Balance



$$v \hat{C}_p \frac{dT}{dt} = v_0 \tilde{C}_p (T_0 - T) + \lambda_1 v (-\Delta H_1^*) + Q - W_s$$

$$\frac{v \hat{C}_p}{v_0 \tilde{C}_p} \frac{dT}{dt} = (T_0 - T) + \frac{\lambda_1 v (-\Delta H_1^*)}{v_0 \tilde{C}_p} + \frac{Q}{v_0 \tilde{C}_p}$$

$$(\tau) \frac{dT}{dt} = (T_0 - T) + \lambda_1 \tau J_1 + \left(\frac{kA}{v_0 \tilde{C}_p} \right) (T_c - T) \quad - (2)$$

$$J_1 = (-\Delta H_1^*) / \tilde{C}_p$$

$$\frac{kA}{v_0 \tilde{C}_p} = \beta$$

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$$\tau \frac{dT}{dt} = \underbrace{(T_0 - T)}_{\downarrow} + \tau J_1 + \beta \underbrace{(T_c - T)}_{=}$$

where $\beta = \frac{hA}{v_0 \tau_p} = \frac{(kg/m^2 \cdot s \cdot f) m^2}{(m^3/s) (kg/m^2 \cdot s \cdot f)} = \text{dimensionless}$

$$\tau \frac{dT}{dt} = [(1 + \beta)(T_c^* - T)] + (\tau J_1) \quad \dots (3)$$

where $T_c^* (1 + \beta) = T_0 + \beta T_c \quad \dots (3a)$

$$\tau \frac{dx}{dt} = -x + \frac{\lambda_1 \tau}{g_{A0}}$$

$$\tau \frac{dT}{dt} = (1+\beta)(T_c^* - T) + \lambda_1 \tau J_1$$

At steady state

$$\tau \frac{dT_s}{dt} = 0 = (1 + \beta) \underbrace{\left(T_c^* - T_s \right)}_{-U_{rs}} + \underbrace{r_{1s} T_1 \tau}_{U_{gs}} \quad (5)$$

$$\tau \frac{dX_s}{dt} = 0 = -X_s + \frac{r_{1s} \tau}{C_{A0}} \quad (4)$$

Let $U_{gs} = r_{1s} \tau T_1$ and

$U_{rs} = (1 + \beta) (T_s - T_c^*)$ so that

steady state is represented by $U_{gs} = U_{rs}$

Example

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$$r_{1s} = k_{1s} C_{As} = k_{1s} C_{A0} (1 - x_s)$$

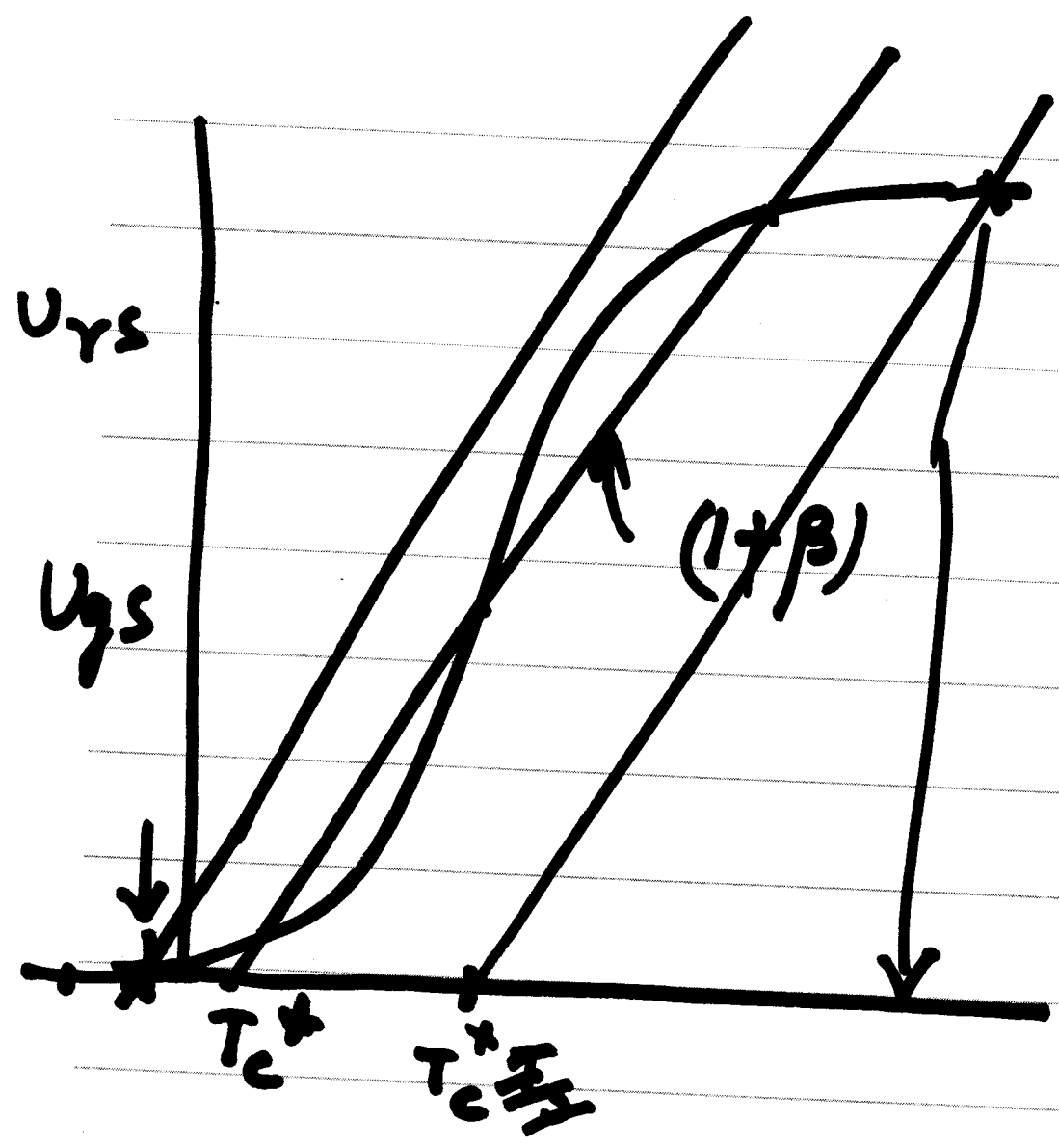
From (4)

$$x_s = k_{1s} C_{A0} (1 - x_s) \tau / C_{A0}$$

$$x_s = k_{1s} \tau (1 - x_s)$$

$$x_s = \frac{k_{1s} \tau}{1 + k_{1s} \tau} = \frac{k_{1s}(\tau) \tau}{(1 + k_{1s}(\tau) \tau)}$$

$$\begin{aligned} U_{gs} &= r_{1s} \tau J_1 = k_{1s} C_{A0} (1 - x_s) \tau J_1 \\ &= (k_{1s} \tau) C_{A0} J_1 / (1 + k_{1s} \tau) = \underline{\underline{C_{A0} x_s J_1}} \end{aligned}$$



$$U_{gs} = \frac{k_{1s} \tau C_{A0} J_1}{1 + k_{1s} \tau}$$

$$U_{rs} = (1 + \beta)(T_s - T_c^*)$$

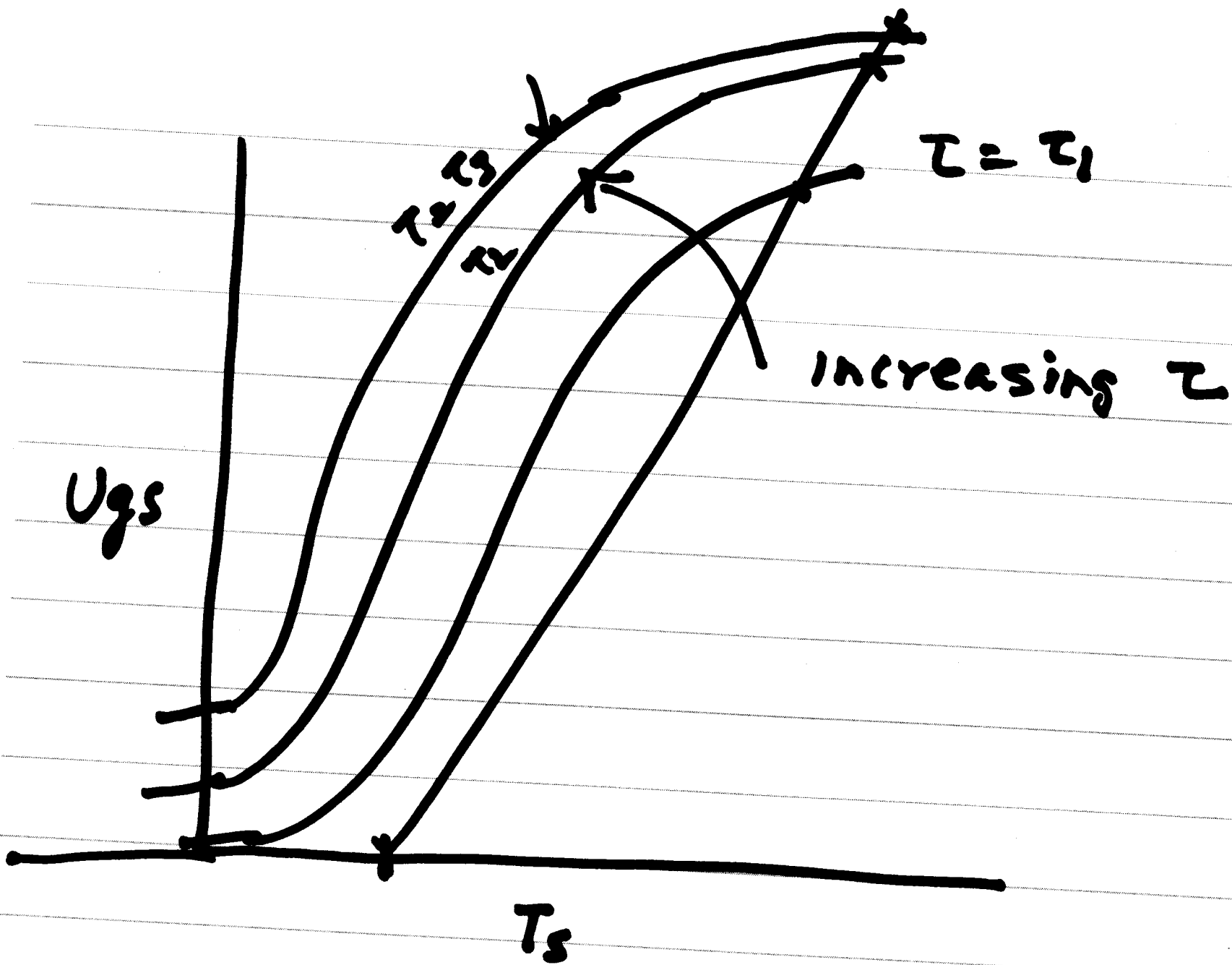
$$U_{gs} = U_{rs}$$

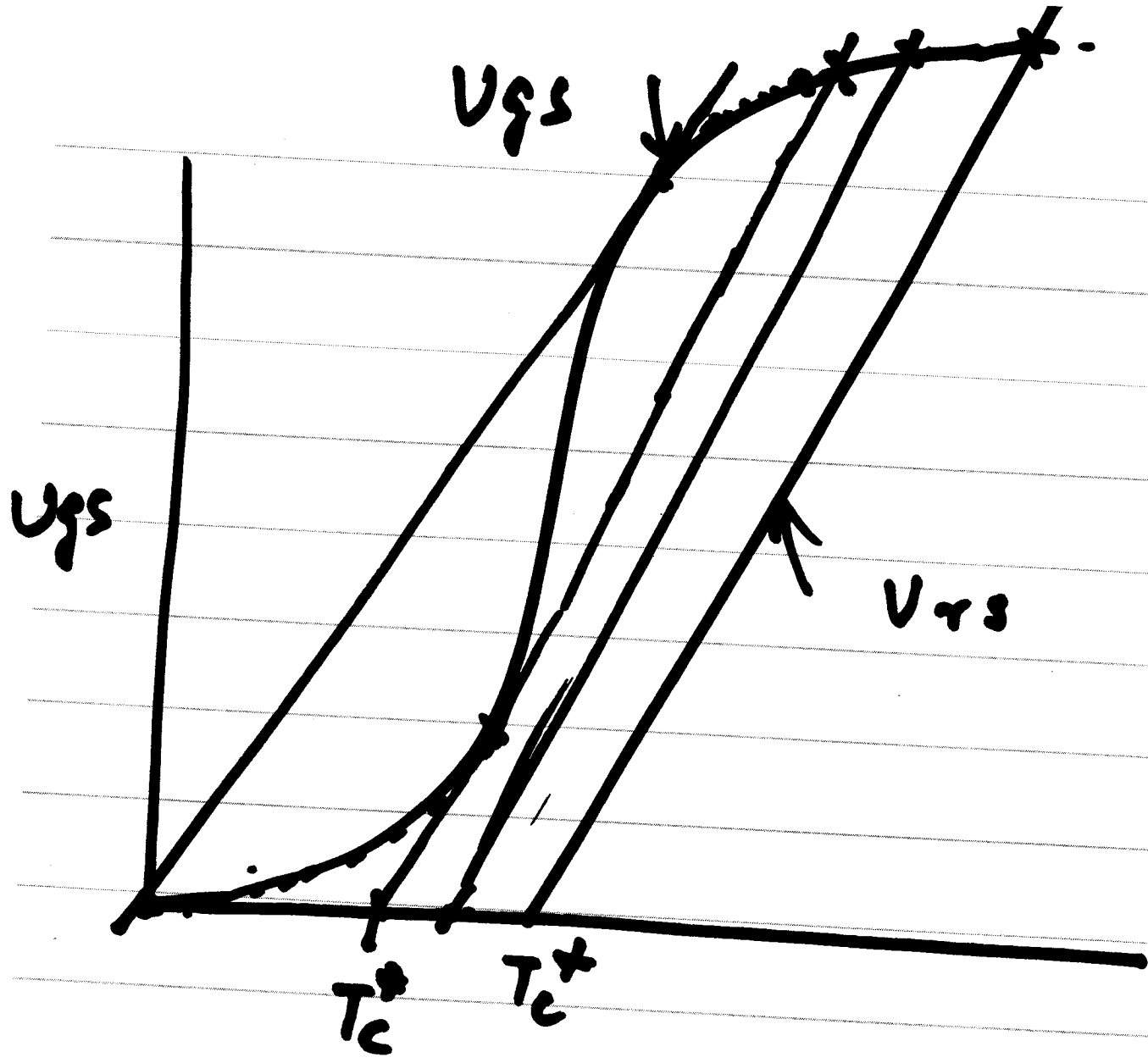
Exothermic Stirred Tank.

1 SS. (Lower

1 SS (upper).

3 SS ()





Stability of steady states.

$$\tau \frac{dx}{dt} = -x + \frac{q_1 \tau}{C_{A0}} \quad (1)$$

$$\tau \frac{dT}{dt} = (1 + \beta)(T_c^* - T) + q_1 \tau J, \quad (2)$$

SS

$$\tau \frac{dx_s}{dt} = 0 = -x_s + q_{1,s} \tau / C_{A0}. \quad (3)$$

$$\tau \frac{dT_s}{dt} = 0 = (1 + \beta)(T_c^* - T_s) + q_{1,s} \tau J, \quad (4)$$

$$\tau \frac{d}{dt} (X - X_s) = -(X - X_s) + (\alpha_1 - \alpha_{1,s}) \frac{\tau}{C_{A_0}} \quad (5)$$

$$\tau \frac{d}{dt} (T - T_s) = -(1 + \beta)(T - T_s) + (\alpha_1 - \alpha_{1,s}) \tau J_1 \quad (6)$$